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## Existence and Non-existence of Solutions for a $(p, q)$-Laplacian Steklov System

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ABSTRACT: In this paper, we study the existence and non-existence of weak solutions to the following system:

$$
\begin{cases}\Delta_{p} u=\Delta_{q} v=0 & \text { in } \Omega \\ |\nabla u|^{p-2} \frac{\partial u}{\partial \nu}=\lambda m|u|^{p-2} u-\varepsilon\left[(\alpha+1)|u|^{\alpha-1} u|v|^{\beta+1}-f\right] & \text { on } \partial \Omega \\ |\nabla v|^{q-2} \frac{\partial v}{\partial \nu}=\lambda n|v|^{q-2} v-\varepsilon\left[(\beta+1)|v|^{\beta-1} v|u|^{\alpha+1}-g\right] & \text { on } \partial \Omega\end{cases}
$$

where $\Omega$ is a bounded domain in $\mathbb{R}^{N}(N \geq 2)$ with a smooth boundary $\partial \Omega, \Delta_{p} u=\operatorname{div}\left(|\nabla u|^{p-2} \nabla u\right)$ is the p-Laplacian, $\frac{\partial}{\partial \nu}$ is the outer normal derivative, $\varepsilon \in\{0,1\}, m, n, f$ and $g$ are the functions that satisfies some conditions.

Key Words: Steklov system, weights, nonlinear boundary conditions, ( $p, q$ )-Lapacian, eigenvalue problem.

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## 1. Introduction

Consider the system with nonlinear boundary conditions

$$
\begin{cases}\Delta_{p} u=\Delta_{q} v=0 & \text { in } \Omega  \tag{1.1}\\ |\nabla u|^{p-2} \frac{\partial u}{\partial \nu}=\lambda m|u|^{p-2} u-\varepsilon\left[(\alpha+1)|u|^{\alpha-1} u|v|^{\beta+1}-f\right] & \text { on } \partial \Omega \\ |\nabla v|^{q-2} \frac{\partial v}{\partial \nu}=\lambda n|v|^{q-2} v-\varepsilon\left[(\beta+1)|v|^{\beta-1} v|u|^{\alpha+1}-g\right] & \text { on } \partial \Omega\end{cases}
$$

where $\Omega$ is a bounded domain in $\mathbb{R}^{N}(N \geq 2)$, with a smooth boundary $\partial \Omega, 1<p<+\infty, 1<q<+\infty$, $\varepsilon \in\{0,1\}$ and suppose the following conditions:
$\alpha \geq 0, \beta \geq 0$ such that $\frac{\alpha+1}{p}+\frac{\beta+1}{q}=1$ and

$$
\begin{gathered}
f \in \mathrm{~L}^{r}(\partial \Omega), r=\frac{p \bar{p}}{p \bar{p}-\bar{p}+1}, \frac{N-1}{p-1}<\bar{p}<\infty \text { if } p<N \text { and } \bar{p} \geq 1 \text { if } p \geq N \\
g \in \mathrm{~L}^{\bar{r}}(\partial \Omega), \bar{r}=\frac{q \bar{q}}{q \bar{q}-\bar{q}+1}, \frac{N-1}{q-1}<\bar{q}<\infty \text { if } q<N \text { and } \bar{q} \geq 1 \text { if } q \geq N \\
M_{\bar{p}}=\left\{m \in \mathrm{~L}^{\overline{\mathrm{p}}}(\partial \Omega), m^{+} \not \equiv 0, \int_{\partial \Omega} m d \sigma<0\right\} \\
M_{\bar{q}}=\left\{m \in \mathrm{~L}^{\overline{\mathrm{q}}}(\partial \Omega), m^{+} \not \equiv 0, \int_{\partial \Omega} m d \sigma<0\right\}
\end{gathered}
$$

$\Delta_{p} u=\operatorname{div}\left(|\nabla u|^{p-2} \nabla u\right)$ is the $p$-Laplacian. The operator $\triangle_{p}$ turns up in many mathematical setting: e.g., non-newtonien fluids, reaction-diffusion problems, porous media, astronomy, etc. (see for example [4]).

[^0]Many publications, such as $[6,8]$, discuss quasilinear elliptic systems involving $p$-Laplacian operators and show the existence and multiplicity of solutions. The authors in [6] studied the existence of solutions for

$$
\begin{cases}-\triangle_{p} u=F_{u}(x, u, v) & \text { in } \Omega \\ -\triangle_{q} v=F_{v}(x, u, v) & \text { in } \Omega \\ u=v=0, & \text { on } \partial \Omega\end{cases}
$$

where $p, q$ are real numbers larger than 1 .
In $[1,5]$, the authors studied a Dirichlet problem involving critical exponents. The author, in [9], has been interested to the system involving $(p(x), q(x))$-laplacian with Dirichlet conditions, which generalize and improve the result of [1].
Existence results for nonlinear elliptic systems when the nonlinear term appears as a source in the equation complemented with Dirichlet boundary conditions have been studied by various authors; we cite the works $[6,10,11]$.

For the nonlinear boundary condition, the authors in [7] proved the existence of nontrivial solutions of the quasi-linear elliptic system.

$$
\begin{cases}\Delta_{p} u=|u|^{p-2} u, \Delta_{q} v=|v|^{q-2} v & \text { in } \Omega \\ |\nabla u|^{p-2} \frac{\partial u}{\partial \nu}=F_{u}(x, u, v),|\nabla v|^{q-2} \frac{\partial v}{\partial \nu}=F_{v}(x, u, v) & \text { on } \partial \Omega\end{cases}
$$

where $\left(F_{u}, F_{v}\right)$ is the gradient of some positive potential $F: \partial \Omega \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$.
The $(p, q)$ harmonic case for the Steklov system has been studied in [2].
In the present paper, we are interested at the existence and non-existence of $(p, q)$-harmonic solutions, $(u, v) \in \mathrm{W}^{1, \mathrm{p}}(\Omega) \times \mathrm{W}^{1, \mathrm{q}}(\Omega)$, for a Steklov system (1.1).

This paper is organized as follows. In section 2 , which has a preliminary character, we collect some results relative to the following Steklov problem (2.1). In section 3, we study the existence and nonexistence solutions for our system (1.1). Our proofs are based on variational arguments.

## 2. Preliminaries

In this section, we collect some results relative to the Steklov eigenvalue problem

$$
\begin{cases}\Delta_{p} u=0 & \text { in } \Omega  \tag{2.1}\\ |\nabla u|^{p-2} \frac{\partial u}{\partial \nu}=\lambda m(x)|u|^{p-2} u & \text { on } \partial \Omega\end{cases}
$$

where the weight $m$ is assumed to lie in $M_{\bar{p}}=\left\{m \in \mathrm{~L}^{\bar{p}}(\partial \Omega), m^{+} \not \equiv 0, \int_{\partial \Omega} m d \sigma<0\right\}$.
O. Torné in [12] showed, by using infinite dimensional Ljusternik-Schnirelman theory, that the problem (2.1) admits a sequence of eigenvalues:

$$
\lambda_{k}(m, p)=\inf _{C \in \Gamma_{k}} \sup _{x \in C} \frac{1}{p} \int_{\Omega}|\nabla u|^{p} d x
$$

where

$$
\Gamma_{k}=\{C \subset S ; C \text { is symmetric, compact and } \gamma(C) \geq K\}
$$

with

$$
S=\left\{u \in \mathrm{~W}^{1, \mathrm{p}}(\Omega) ; \frac{1}{p} \int_{\partial \Omega} m|u|^{P} d \sigma=1\right\} \text { and } \gamma(C) \text { is the Krasnoselski genus of C. }
$$

Let $\lambda_{1}(m, p)=\inf \left\{\frac{1}{p} \int_{\Omega}|\nabla u|^{p} d x ; u \in \mathrm{~W}^{1, \mathrm{p}}(\Omega)\right.$ and $\left.\frac{1}{p} \int_{\partial \Omega} m|u|^{P} d \sigma=1\right\}$.
This author also showed that if $\int_{\partial \Omega} m d \sigma<0$, then $\lambda_{1}(m, p)>0$.
In [3], A. Anane et al have also proved that there exists an increasing unbounded sequence of positive eigenvalues for the problem (2.1) but by applying an other deformation lemma.
In [3] the authors showed the following result.
Theorem 2.1. 1. If $m, m_{0} \in M_{\bar{p}}$, then we have

$$
\frac{1}{\lambda_{1}}:=\frac{1}{\lambda_{1}(m, p)}=\sup _{u \in A} \frac{1}{p} \int_{\partial \Omega} m|u|^{p} d \sigma
$$

where

$$
A=\left\{u \in W^{1, p}(\Omega) ; \frac{1}{p} \int_{\Omega}|\nabla u|^{p} d x=1\right\}
$$

2. If $m \leq \not \equiv m_{0}$, then $\lambda_{1}\left(m_{0}, p\right)<\lambda_{1}(m, p)$.

## 3. Existence and nonexistence of solutions for a Steklov system

In this section, where $\varepsilon=1$, we show that the problem (1.1), admits at least a nontrivial solution under some conditions on the positive number $\lambda$, we also show the non-existence results for nontrivial solutions of the system (1.1) in the case $\varepsilon=0$. The following theorem is the main result in this paper.

Theorem 3.1. Let $m \in M_{\bar{p}}, n \in M_{\bar{q}}$ and $0<\lambda<\inf \left(\lambda_{1}(m, p), \lambda_{1}(n, q)\right)$. Then

1. If $\varepsilon=1$, the system (1.1) admits at least a solution for any $f, g$.
2. If $\varepsilon=0$, the system (1.1) has no non-trivial solutions.

Consider the space $\mathrm{W}=\mathrm{W}^{1, \mathrm{p}}(\Omega) \times \mathrm{W}^{1, \mathrm{q}}(\Omega)$ equipped with the norm

$$
\|w\|=\|u\|_{1, p}+\|v\|_{1, q}, \text { for } w=(u, v) \in \mathrm{W}
$$

where

$$
\|u\|_{1, p}=\left(\int_{\Omega}|\nabla u|^{p} d x+\int_{\Omega}|u|^{p} d x\right)^{\frac{1}{p}}
$$

and

$$
\|v\|_{1, q}=\left(\int_{\Omega}|\nabla v|^{q} d x+\int_{\Omega}|v|^{q} d x\right)^{\frac{1}{q}}
$$

We say that $(u, v) \in \mathrm{W}^{1, \mathrm{p}}(\Omega) \times \mathrm{W}^{1, \mathrm{q}}(\Omega)$ is a weak solution of $(1.1)$ if :

$$
\begin{aligned}
\int_{\Omega}|\nabla u|^{p-2} \nabla u \nabla \varphi d x & =\int_{\partial \Omega} \lambda m|u|^{p-2} u \varphi d \sigma-\varepsilon\left[(\alpha+1) \int_{\partial \Omega}|u|^{\alpha-1} u|v|^{\beta+1} \varphi d \sigma-\int_{\partial \Omega} f \varphi d \sigma\right] \\
\int_{\Omega}|\nabla v|^{q-2} \nabla v \nabla \psi d x & =\int_{\partial \Omega} \lambda n|v|^{q-2} v \psi d \sigma-\varepsilon\left[(\beta+1) \int_{\partial \Omega}|v|^{\beta-1} v|u|^{\alpha+1} \psi d \sigma+\int_{\partial \Omega} g \psi d \sigma\right]
\end{aligned}
$$

for all $(\varphi, \psi) \in \mathrm{W}^{1, \mathrm{p}}(\Omega) \times \mathrm{W}^{1, \mathrm{q}}(\Omega)$, where $d \sigma$ is the $N-1$ dimensional Hausdroff measure.
The energy functional corresponding to the system (1.1) is the functional $\Phi_{\varepsilon}$ such that $\Phi_{\varepsilon}: W \rightarrow \mathbb{R}$ with

$$
\begin{aligned}
\Phi_{\varepsilon}(u, v)= & \frac{1}{p} \int_{\Omega}|\nabla u|^{p} d x-\frac{\lambda}{p} \int_{\partial \Omega} m|u|^{p} d \sigma+\frac{1}{q} \int_{\Omega}|\nabla v|^{q} d x-\frac{\lambda}{q} \int_{\partial \Omega} n|v|^{q} d \sigma \\
& +\varepsilon\left[\int_{\partial \Omega}|u|^{\alpha+1}|v|^{\beta+1} d \sigma-\int_{\partial \Omega} f u d \sigma-\int_{\partial \Omega} g v d \sigma\right]
\end{aligned}
$$

It is clear that the critical points of the energy functional $\Phi_{\varepsilon}$ are the weak solutions of the system (1.1). To prove the Theorem (3.1), we need the following lemmas.

Lemma 3.2. If $\varepsilon=1, m \in M_{\bar{p}}$ and $n \in M_{\bar{q}}$, then the functional $\Phi_{\varepsilon=1}$ is coercive for, $0<\lambda<$ $\inf \left(\lambda_{1}(m, p), \lambda_{1}(n, q)\right)$.

Proof. Suppose by contradiction that $\Phi_{\varepsilon=1}$ is not coercive. Then there exist a sequence $w_{n} \in \mathrm{~W}$ and $c \geq 0$ with $w_{n}=\left(u_{n}, v_{n}\right)$ such that $\left\|w_{n}\right\| \rightarrow+\infty$ and $\left|\Phi_{\varepsilon=1}\left(w_{n}\right)\right| \leq c$.
The condition $\left|\Phi_{\varepsilon=1}\left(w_{n}\right)\right| \leq c$ implies that

$$
\begin{gathered}
\frac{1}{p} \int_{\Omega}\left|\nabla u_{n}\right|^{p} d x-\frac{\lambda}{p} \int_{\partial \Omega} m\left|u_{n}\right|^{p} d \sigma+\frac{1}{q} \int_{\Omega}\left|\nabla v_{n}\right|^{q} d x-\frac{\lambda}{q} \int_{\partial \Omega} n\left|v_{n}\right|^{q} d \sigma \\
\quad+\int_{\partial \Omega}\left|u_{n}\right|^{\alpha+1}\left|v_{n}\right|^{\beta+1} d \sigma-\int_{\partial \Omega} f u_{n} d \sigma-\int_{\partial \Omega} g v_{n} d \sigma \leq c
\end{gathered}
$$

Since

$$
\int_{\partial \Omega}\left|u_{n}\right|^{\alpha+1}\left|v_{n}\right|^{\beta+1} d \sigma \geq 0
$$

then

$$
\begin{aligned}
\frac{1}{p} \int_{\Omega}\left|\nabla u_{n}\right|^{p} d x-\frac{\lambda}{p} & \int_{\partial \Omega} m\left|u_{n}\right|^{p} d \sigma+\frac{1}{q} \int_{\Omega}\left|\nabla v_{n}\right|^{q} d x-\frac{\lambda}{q} \int_{\partial \Omega} n\left|v_{n}\right|^{q} d \sigma \\
& -\int_{\partial \Omega} f u_{n} d \sigma-\int_{\partial \Omega} g v_{n} d \sigma \leq c
\end{aligned}
$$

Thus

$$
\begin{equation*}
\frac{1}{p} \int_{\Omega}\left|\nabla u_{n}\right|^{p} d x-\frac{\lambda}{p} \int_{\partial \Omega} m\left|u_{n}\right|^{p} d \sigma-\int_{\partial \Omega} f u_{n} d \sigma-\int_{\partial \Omega} g v_{n} d \sigma \leq c \tag{3.1}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{1}{q} \int_{\Omega}\left|\nabla v_{n}\right|^{q} d x-\frac{\lambda}{q} \int_{\partial \Omega} n\left|v_{n}\right|^{q} d \sigma-\int_{\partial \Omega} f u_{n} d \sigma-\int_{\partial \Omega} g v_{n} d \sigma \leq c \tag{3.2}
\end{equation*}
$$

As $0<\lambda<\inf \left(\lambda_{1}(m, p), \lambda_{1}(n, q)\right)$, then we have

$$
\left(1-\frac{\lambda}{\lambda_{1}(m, p)}\right) \frac{1}{p} \int_{\Omega}\left|\nabla u_{n}\right|^{p} d x-\int_{\partial \Omega} f u_{n} d \sigma-\int_{\partial \Omega} g v_{n} d \sigma \leq c
$$

and

$$
\left(1-\frac{\lambda}{\lambda_{1}(n, q)}\right) \frac{1}{q} \int_{\Omega}\left|\nabla v_{n}\right|^{q} d x-\int_{\partial \Omega} f u_{n} d \sigma-\int_{\partial \Omega} g v_{n} d \sigma \leq c
$$

Put $\tilde{u}_{n}=\frac{u_{n}}{\left\|w_{n}\right\|}$ and $\tilde{v}_{n}=\frac{v_{n}}{\left\|w_{n}\right\|}$, dividing by $\left\|w_{n}\right\|^{p}$ and $\left\|w_{n}\right\|^{q}$, we obtain

$$
\begin{aligned}
& \left(1-\frac{\lambda}{\lambda_{1}(m, p)}\right) \frac{1}{p} \int_{\Omega}\left|\nabla \tilde{u}_{n}\right|^{p} d x-\frac{1}{\left\|w_{n}\right\|^{p}}\left(\int_{\partial \Omega} f u_{n} d \sigma+\int_{\partial \Omega} g v_{n} d \sigma\right) \leq \frac{c}{\left\|w_{n}\right\|^{p}} \\
& \left(1-\frac{\lambda}{\lambda_{1}(n, q)}\right) \frac{1}{q} \int_{\Omega}\left|\nabla \tilde{v}_{n}\right|^{q} d x-\frac{1}{\left\|w_{n}\right\|^{q}}\left(\int_{\partial \Omega} f u_{n} d \sigma-\int_{\partial \Omega} g v_{n} d \sigma\right) \leq \frac{c}{\left\|w_{n}\right\|^{q}}
\end{aligned}
$$

Since $\tilde{u}_{n}$ is bounded, for a further subsequence still denoted $\tilde{u}_{n}, \tilde{u}_{n} \rightharpoonup \tilde{u}$ weakly in $\mathrm{W}^{1, \mathrm{p}}(\Omega)$ and $\tilde{u}_{n} \rightarrow \tilde{u}$ strongly in $\mathrm{L}^{\mathrm{p}}(\Omega)$. On the other hand, we have

$$
\int_{\Omega}|\nabla \tilde{u}|^{p} d x+\int_{\Omega}|\tilde{u}|^{p} d x \leq \liminf _{n \longrightarrow+\infty}\left(\int_{\Omega}\left|\nabla \tilde{u}_{n}\right|^{p} d x+\int_{\Omega}\left|\tilde{u}_{n}\right|^{p} d x\right)
$$

Passing to the limit, we obtain $\frac{1}{p} \int_{\Omega}|\nabla \tilde{u}|^{p} d x=0$. Thus $\tilde{u}=c s t=c_{1}$ and $\left\|\tilde{u}_{n}\right\|_{1, p} \longrightarrow\|\tilde{u}\|_{1, p}$. Since $\mathrm{W}^{1, \mathrm{p}}(\Omega)$ is uniformly convex and reflexive, $\tilde{u}_{n} \longrightarrow c s t=c_{1}$ strongly in $\mathrm{W}^{1, \mathrm{p}}(\Omega)$. By a similar argument, we show that $\tilde{v}_{n} \longrightarrow c s t=c_{2}$ strongly in $\mathrm{W}^{1, \mathrm{q}}(\Omega)$.
Dividing (3.1) and (3.2) respectively by $\left\|w_{n}\right\|^{p}$ and $\left\|w_{n}\right\|^{q}$ and passing to the limit, we obtain

$$
-\frac{\lambda\left|c_{1}\right|^{p}}{p} \int_{\partial \Omega} m d \sigma \leq 0
$$

and

$$
-\frac{\lambda\left|c_{2}\right|^{q}}{q} \int_{\partial \Omega} n d \sigma \leq 0
$$

Since $\int_{\partial \Omega} m d \sigma<0$ and $\int_{\partial \Omega} n d \sigma<0$, then $c_{1}=c_{2}=0$. Consequently $\left\|\tilde{w}_{n}\right\| \longrightarrow 0$, where $\tilde{w}_{n}=\left(\tilde{u}_{n}, \tilde{v}_{n}\right)$. This contradicts $\left\|\tilde{w}_{n}\right\|=1$. Finally, $\Phi_{\varepsilon=1}$ is coercive.

Lemma 3.3. If $m \in M_{\bar{p}}$ and $n \in M_{\bar{q}}$, then the energy functional $\Phi_{\varepsilon=1}$ is a weakly lower semicontinuous.

Proof. It suffices to see that the trace mapping $\mathrm{W} \longrightarrow \mathrm{L}^{\frac{\mathrm{p} \bar{p}}{\mathrm{p}-1}}(\partial \Omega) \times \mathrm{L}^{\frac{\mathrm{q} \overline{\bar{q}}}{\mathrm{q}-1}}(\partial \Omega)$ is compact. Indeed, if we have $\mathrm{W}^{1, \mathrm{p}}(\Omega) \times \mathrm{W}^{1, \mathrm{q}}(\Omega) \subset \mathrm{L}^{\frac{\mathrm{p} \bar{p}}{\mathrm{p}-1}}(\partial \Omega) \times \mathrm{L}^{\frac{\mathrm{q} \bar{q}}{\mathrm{q}-1}}(\partial \Omega)$ with compact injection, then for any bounded part in W , it is relatively compact in $\mathrm{L}^{\frac{\mathrm{p} \overline{\mathrm{p}}}{\mathrm{p}-1}}(\partial \Omega) \times \mathrm{L}^{\frac{\mathrm{q} \overline{\mathrm{q}}}{\mathrm{q}-1}}(\partial \Omega)$.
Let $\left(u_{n}, v_{n}\right)$ be a bounded sequence in W , it means that $u_{n}$ is bounded in $\mathrm{W}^{1, \mathrm{p}}(\Omega)$ and $v_{n}$ is bounded in $\mathrm{W}^{1, \mathrm{q}}(\Omega)$. For the subsequences, there exists $(u, v) \in \mathrm{W}^{1, \mathrm{p}}(\Omega) \times \mathrm{W}^{1, \mathrm{q}}(\Omega)$ such that $u_{n} \rightharpoonup u$ weakly in $\mathrm{W}^{1, \mathrm{p}}(\Omega)$, strongly in $\mathrm{L}^{\mathrm{p}}(\Omega)$ and $\mathrm{L}^{\frac{\mathrm{p}}{\mathrm{p}}-1}(\partial \Omega)$ and $v_{n} \rightharpoonup v$ weakly in $\mathrm{W}^{1, \mathrm{q}}(\Omega)$, strongly in $\mathrm{L}^{\mathrm{q}}(\Omega)$ and $L^{\frac{\mathrm{q} \overline{\mathrm{q}}}{\mathrm{p}-1}}(\partial \Omega)$. Thus

$$
\int_{\Omega}|\nabla u|^{p} d x \leq \liminf _{n \rightarrow \infty} \int_{\Omega}\left|\nabla u_{n}\right|^{p} d x
$$

and

$$
\begin{gathered}
\frac{1}{p} \int_{\Omega}|\nabla u|^{p} d x-\frac{\lambda}{p} \int_{\partial \Omega} m|u|^{p} d \sigma+\int_{\partial \Omega}|u|^{\alpha+1}|v|^{\beta+1} d \sigma-\int_{\partial \Omega} f u d \sigma \leq \\
\liminf _{n \rightarrow \infty}\left[\frac{1}{p} \int_{\Omega}\left|\nabla u_{n}\right|^{p} d x-\frac{\lambda}{p} \int_{\partial \Omega} m\left|u_{n}\right|^{p} d \sigma+\int_{\partial \Omega}\left|u_{n}\right|^{\alpha+1}\left|v_{n}\right|^{\beta+1} d \sigma-\int_{\partial \Omega} f u_{n} d \sigma\right] .
\end{gathered}
$$

We have the same result, if we replace $u_{n}$ by $v_{n}$. This implies that

$$
\Phi_{\varepsilon=1}(u, v) \leq \liminf _{n \rightarrow \infty} \Phi_{\varepsilon=1}\left(u_{n}, v_{n}\right)
$$

consequently $\Phi_{\varepsilon=1}$ is weakly lower semi-continuous.

Proof of Theorem 3.1. 1. By Lemma 3.2, $\Phi_{\varepsilon=1}$ is coercive and by Lemma $3.3 \Phi_{\varepsilon=1}$ is weakly lower semicontinuous. Furthermore $\Phi_{\varepsilon=1}$ is continuously differentiable.Thus the proof is complete by using the minimum principle.
2. For $\varepsilon=0$, the system (1.1) becomes

$$
\begin{cases}\Delta_{p} u=\Delta_{q} v=0 & \text { in } \Omega  \tag{3.3}\\ |\nabla u|^{p-2} \frac{\partial u}{\partial \nu}=\lambda m|u|^{p-2} u & \text { on } \partial \Omega \\ |\nabla v|^{q-2} \frac{\partial v}{\partial \nu}=\lambda n|v|^{q-2} v & \text { on } \partial \Omega\end{cases}
$$

Affirm that if $0<\lambda<\inf \left(\lambda_{1}(m, p), \lambda_{1}(n, q)\right)$, then the system (3.3) has no non-trivial solution. Indeed, suppose, by contradiction, that the system (3.3) have a non-trivial solution $(u, v)$ such that $u \neq 0$ or $v \neq 0$. Then, we obtain

$$
\begin{aligned}
\int_{\Omega}|\nabla u|^{p-2} \nabla u \nabla \varphi d x & =\int_{\partial \Omega} \lambda m|u|^{p-2} u \varphi d \sigma \\
\int_{\Omega}|\nabla v|^{q-2} \nabla v \nabla \phi d x & =\int_{\partial \Omega} \lambda n|v|^{q-2} v \phi d \sigma
\end{aligned}
$$

For all $(\varphi, \psi) \in \mathrm{W}^{1, \mathrm{p}}(\Omega) \times \mathrm{W}^{1, \mathrm{q}}(\Omega)$. Thus for $\varphi=u$ and $\psi=v$, we obtain

$$
\int_{\Omega}|\nabla u|^{p} d x=\lambda \int_{\partial \Omega} m|u|^{p} d \sigma \text { and } \int_{\Omega}|\nabla v|^{q} d x=\lambda \int_{\partial \Omega} n|v|^{q} d \sigma
$$

So, we distinguish two cases:

1. If $\int_{\Omega}|\nabla u|^{p} d x=\int_{\Omega}|\nabla v|^{q} d x=0$, then $u=c s t$ and $v=c s t$. So, we have $0=\lambda|c s t|^{p} \int_{\partial \Omega} m d \sigma$ and $0=\lambda|c s t|^{q} \int_{\partial \Omega} n d \sigma$. Since $\int_{\partial \Omega} m d \sigma<0$ and $\int_{\partial \Omega} n d \sigma<0, u=v=0$. This contradicts the fact that $u \neq 0$ or $v \neq 0$.
2. If $\int_{\Omega}|\nabla u|^{p} d x>0$ or $\int_{\Omega}|\nabla v|^{q} d x>0$, then

$$
0<\frac{\int_{\Omega}|\nabla u|^{p} d x}{\int_{\partial \Omega} m|u|^{p} d \sigma}=\lambda \text { or } 0<\frac{\int_{\Omega}|\nabla v|^{q} d x}{\int_{\partial \Omega} n|v|^{q} d \sigma}=\lambda .
$$

Thus

$$
\lambda_{1}(m, p) \leq \frac{\int_{\Omega}|\nabla u|^{p} d x}{\int_{\partial \Omega} m|u|^{p} d \sigma}=\lambda \text { or } \lambda_{1}(n, q) \leq \frac{\int_{\Omega}|\nabla v|^{q} d x}{\int_{\partial \Omega} n|v|^{p} d \sigma}=\lambda
$$

So

$$
\lambda_{1}(m, p) \leq \lambda \text { or } \lambda_{1}(n, q) \leq \lambda
$$

It follows that

$$
\inf \left(\lambda_{1}(m, p), \lambda_{1}(n, q)\right) \leq \lambda
$$

This contradicts our assumption.

Corollary 3.4. 1. For $\varepsilon=1$, let $m, m_{0} \in M_{\bar{p}}$ and $n, n_{0} \in M_{\bar{q}}$, if $m \leq \not \equiv m_{0}, n \leq \not \equiv n_{0}$ on $\partial \Omega$ and $\lambda=\lambda_{1}\left(m_{0}, p\right)=\lambda_{1}\left(n_{0}, q\right)$, then the system (1.1) admits at least a solution for any $f, g$.
2. For $\varepsilon=0$, let $m \in M_{\bar{p}}$, $n \in M_{\bar{q}}$, if $0<\lambda \leq \inf \left(\lambda_{1}(m, p), \lambda_{1}(n, q)\right)<\sup \left(\lambda_{1}(m, p), \lambda_{1}(n, q)\right)$, then the system (1.1) has no non-trivial solution $(u, v) \in W$ in the sense that $u \not \equiv 0$ and $v \not \equiv 0$.
3. For $\varepsilon=0$, let $m \in M_{\bar{p}}, n \in M_{\bar{q}}$, if $\left.\lambda=\lambda_{1}(m, p)=\lambda_{1}(n, q)\right)$, then the system (1.1) has infinitely many solutions.

Proof. 1. Let $m, m_{0} \in M_{\bar{p}}, n, n_{0} \in M_{\bar{q}}$, by Theorem 2.1, if $m \leq \not \equiv m_{0}$ and $n \leq \not \equiv n_{0}$, then $\lambda=$ $\lambda_{1}\left(m_{0}, p\right)<\lambda_{1}(m, p)$, and $\lambda=\lambda_{1}\left(n_{0}, q\right)<\lambda_{1}(n, q)$ this implies that $\lambda<\inf \left(\lambda_{1}(m, p), \lambda_{1}(n, q)\right)$. According to Theorem 3.1 the proof is complete.
2. - if $0<\lambda<\inf \left(\lambda_{1}(m, p), \lambda_{1}(n, q)\right)$, we use the Theorem 2.1.

- If $0<\lambda=\inf \left(\lambda_{1}(m, p), \lambda_{1}(n, q)\right)<\sup \left(\lambda_{1}(m, p), \lambda_{1}(n, q)\right)$, then we have two cases. First case: if $\lambda=\lambda_{1}(m, p)<\lambda_{1}(n, q)$ ), the non-trivial solutions are of the form $\left(\alpha \varphi_{1}(m, p), 0\right)$, where $\varphi_{1}(m, p)$ is an eigenfunction of system (2.1) associated to $\lambda_{1}(m, p)$.
Second case: if $\left.\lambda=\lambda_{1}(n, q)<\lambda_{1}(m, p)\right)$, the non-trivial solutions are of the form $\left(0, \beta \varphi_{1}(n, q)\right)$, where $\varphi_{1}(n, q)$ is an eigenfunction of system (2.1) (with $q$ and $n$ instead $p$ and $m$ ) of associated to $\lambda_{1}(n, q)$.

3. We use the simplicity of the first eigenvalue $\lambda_{1}(k, r)$ of the system (2.1), where $k \equiv m$ and $r=p$ or $k \equiv n$ and $r=q$.

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