



Characterizing Inequalities for Contact CR-warped Product Submanifolds of Generalized Sasakian Space Forms Admitting a Nearly Cosymplectic Structure

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ABSTRACT: This paper studies the contact CR-warped product submanifolds of a generalized Sasakian space form admitting a nearly cosymplectic structure. Some inequalities for existence of these types of warped product submanifolds are established, the obtained inequalities generalize the results that have acquired in [14]. Moreover, we also estimate another inequality for the second fundamental form in the expressions of the warping function, this inequality also generalize the inequalities that have obtained in [19]. In addition, we also explore the equality cases.

Key Words: Nearly cosymplectic manifold, Contact CR-submanifolds, Warped product.

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1. Introduction

It is illustrious that warped products of manifolds perform an significant role in differential geometry, the theory of relativity and mathematical physics. One of the most important examples of a warped product manifold is the excellent setting to the model spacetime close to black holes or bodies with high gravitational fields [20].

The concept of the warped products for the theory of submanifolds was first investigated by B. Y. Chen [2]. Basically, Chen worked out CR-warped product submanifolds in the background of Kaehler manifolds and established a sharp estimate for the length of the second fundamental form in the expressions of warping function. Motivated by Chen, I. Mihai ([10], [11]) studied the contact version of these warped products and acquired the similar estimate for the contact CR-warped product submanifolds of a Sasakian space form. In this line of research many articles have appeared in the setting of almost contact metric manifolds ([8], [12], [15], [18]). K. A. Khan et al. [13] deliberate the existence and nonexistence for the warped product submanifolds of the cosymplectic manifolds and a step forward was made by M. Atceken [14] who proved a characterizing inequality for the existence of the contact CR-warped product submanifolds of a cosymplectic space form.

In this paper, we achieve a characterization for the existence of the contact CR-warped product submanifolds isometrically immersed in a generalized Sasakian space form admitting a nearly cosymplectic structure and as a special case, we also discuss the existence of these warped products for the cosymplectic space forms. Moreover, we prove an estimate for the length of the second fundamental form in the expressions of warping function and some special conditions are also investigated.

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2. Preliminaries

Following [7] a $(2n + 1)$ -dimensional C^∞ -manifold \bar{M} is said to have an almost contact structure if there exist on \bar{M} a tensor field ϕ of type $(1, 1)$, a vector field ξ_1 and a 1-form η_1 satisfying

$$\phi^2 = -I + \eta_1 \otimes \xi_1, \quad \phi\xi_1 = 0, \quad \eta_1 \circ \phi = 0, \quad \eta_1(\xi_1) = 1. \quad (2.1)$$

There always exists a Riemannian metric g on an almost contact metric manifold \bar{M} satisfying the subsequent conditions

$$\eta_1(U_1) = g(U_1, \xi_1), \quad g(\phi U_1, \phi V_1) = g(U_1, V_1) - \eta_1(U_1)\eta_1(V_1), \quad (2.2)$$

for all $U_1, V_1 \in T\bar{M}$.

An almost contact structure (ϕ, ξ_1, η_1) is said to be normal, if the almost complex structure J on the product manifold $\bar{M} \times R$ is given by

$$J(U_1, \lambda \frac{d}{dx}) = (\phi U_1 - \lambda \xi_1, \eta_1(U_1) \frac{d}{dx}),$$

where λ is a C^∞ -function on $\bar{M} \times R$ has no torsion that is J is integrable and the condition for normality in terms of ϕ, ξ_1 and η_1 is $[\phi, \phi] + 2d\eta_1 \otimes \xi_1 = 0$ on \bar{M} , where $[\phi, \phi]$ is the Nijenhuis tensor of ϕ . The *fundamental 2-form* Φ_1 is defined by $\Phi_1(U_1, V_1) = g(U_1, \phi V_1)$.

An almost contact metric structure (ϕ, ξ_1, η_1, g) on \bar{M} is said to be cosymplectic if it is normal and both ϕ and η_1 are closed and the manifold \bar{M} with the cosymplectic structure (ϕ, ξ_1, η_1, g) is said to be a cosymplectic manifold [5]. Moreover, the structure (ϕ, ξ_1, η_1, g) on \bar{M} is said to be nearly cosymplectic if ϕ is of killing type. The manifold \bar{M} equipped with a nearly cosymplectic structure is said to be a nearly cosymplectic manifold. The characteristic equation for the nearly cosymplectic manifolds is described by

$$(\bar{\nabla}_{U_1} \phi)U_1 = 0, \quad (2.3)$$

for any $U_1 \in T\bar{M}$, where $\bar{\nabla}$ is the Riemannian connection of the metric g on \bar{M} .

In [16] Alegre et al. determined the concept of generalized Sasakian space form as that an almost contact metric manifold $(\bar{M}, \phi, \xi_1, \eta_1, g)$ whose curvature tensor \bar{R} satisfies

$$\begin{aligned} \bar{R}(U_1, V_1)W_1 &= f_1\{g(V_1, W_1)U_1 - g(U_1, W_1)V_1\} \\ &+ f_2\{g(U_1, \phi W_1)\phi V_1 - g(V_1, \phi W_1)\phi U_1 \\ &+ 2g(U_1, \phi V_1)\phi W_1\} + f_3\{\eta_1(U_1)\eta_1(W_1)V_1 \\ &- \eta_1(V_1)\eta_1(W_1)U_1 + g(U_1, W_1)\eta_1(V_1)\xi_1 \\ &- g(V_1, W_1)\eta_1(U_1)\xi_1\}, \end{aligned} \quad (2.4)$$

\forall vector fields $U_1, V_1, W_1 \in T\bar{M}$, and three differentiable functions f_1, f_2, f_3 on \bar{M} . A generalized Sasakian space form with functions f_1, f_2, f_3 is denoted by $\bar{M}(f_1, f_2, f_3)$. If $f_1 = \frac{c+3}{4}$, $f_2 = f_3 = \frac{c-1}{4}$, then $\bar{M}(f_1, f_2, f_3)$ is a Sasakian space form $\bar{M}(c)$ [7]. If $f_1 = \frac{c-3}{4}$, $f_2 = f_3 = \frac{c+1}{4}$, then $\bar{M}(f_1, f_2, f_3)$ is a Kenmotsu space form $\bar{M}(c)$ [12], and if $f_1 = f_2 = f_3 = \frac{c}{4}$, then $\bar{M}(f_1, f_2, f_3)$ is a cosymplectic space form $\bar{M}(c)$ [16].

For a submanifold M of a Riemannian manifold \bar{M} with induced metric g , the Gauss and Weingarten formulae are governed by the following equations

$$\bar{\nabla}_{U_1} V_1 = \nabla_{U_1} V_1 + \sigma(U_1, V_1), \quad (2.5)$$

$$\bar{\nabla}_{U_1} N = -A_N U_1 + \nabla_{U_1}^\perp N, \quad (2.6)$$

where ∇ and ∇^\perp are the induced connections on the tangent bundle TM and normal bundle $T^\perp M$ of M , for any $U_1, V_1 \in TM, N \in T^\perp M$. The second fundamental form and the shape operator for the immersion of M in \bar{M} are denoted by σ and A_N respectively, and they are associated by

$$g(\sigma(U_1, V_1), N) = g(A_N U_1, V_1), \quad (2.7)$$

where g represents the Riemannian metric on \bar{M} as well as on M .

We have the following formula for squared norm of σ

$$\|\sigma\|^2 = \sum_{i,j=1}^k g(\sigma(u_i, u_j), \sigma(u_i, u_j)),$$

where $\{u_1, u_2, \dots, u_k\}$ is a local orthonormal set of vector fields on M .

A submanifold M of \bar{M} is said to be a totally geodesic submanifold if $\sigma(U_1, V_1) = 0, \forall U_1, V_1 \in TM$, and totally umbilical submanifold if $\sigma(U_1, V_1) = g(U_1, V_1)H$, where H is the mean curvature vector.

For any $V_1 \in TM$, we write

$$\phi V_1 = PV_1 + FV_1, \quad (2.8)$$

where PV_1 and FV_1 are the tangential and normal parts of ϕV_1 correspondingly.

The covariant differentiation of the tensors ϕ, P , and F are illustrated respectively, as follows

$$(\bar{\nabla}_{U_1} \phi)V_1 = \bar{\nabla}_{U_1} \phi V_1 - \phi \bar{\nabla}_{U_1} V_1, \quad (2.9)$$

$$(\bar{\nabla}_{U_1} P)V_1 = \nabla_{U_1} P V_1 - P \nabla_{U_1} V_1, \quad (2.10)$$

$$(\bar{\nabla}_{U_1} F)V_1 = \nabla_{U_1}^\perp F V_1 - F \nabla_{U_1} V_1 \quad (2.11)$$

Additionally, for any $U_1, V_1 \in TM$, the tangential and normal components of $(\bar{\nabla}_{U_1} \phi)V_1$ are symbolized by $P_{U_1} V_1$ and $Q_{U_1} V_1$ i.e.,

$$(\bar{\nabla}_{U_1} \phi)V_1 = P_{U_1} V_1 + Q_{U_1} V_1. \quad (2.12)$$

By (2.3) and (2.12), it is easy to see that

$$(a) P_{U_1} V_1 = -P_{V_1} U_1, \quad (b) Q_{U_1} V_1 = -Q_{V_1} U_1, \quad (2.13)$$

for any $U_1, V_1 \in TM$.

Definition 2.1. An m -dimensional Riemannian submanifold M of an almost contact metric manifold \bar{M} , such that ξ_1 is tangent to M is said to be a contact CR-submanifold if there exist two orthogonal complementary distributions D^T and D^\perp such that D^T is invariant i.e., $\phi D^T \subseteq D^T$ and D^\perp is anti invariant i.e., $\phi D^\perp \subseteq T^\perp M$.

Then for a contact CR-submanifold \bar{M} , the tangent bundle TM of M can be written as follows

$$TM = D^T \oplus D^\perp \oplus \langle \xi_1 \rangle,$$

where $\langle \xi_1 \rangle$ represents the 1-dimensional distribution spanned by ξ_1 .

The normal bundle $T^\perp M$ can be decomposed as follows

$$T^\perp M = \mu \oplus \phi D^\perp, \quad (2.14)$$

where μ is the invariant subspace of $T^\perp M$.

A contact CR-submanifold M of an almost contact metric manifold \bar{M} is called contact CR-product if the distributions D and D^\perp are parallel on M . The warped product of Riemannian manifolds is the generalization of the product manifolds, which is defined as follows

Definition 2.2. Let (R, g_R) and (S, g_S) be two Riemannian manifolds with Riemannian metrics g_R and g_S respectively and ψ be a positive differentiable function on R . The warped product of R and S is the Riemannian manifold $(R \times S, g)$, where

$$g = g_R + \psi^2 g_S \quad (2.15)$$

The warped product manifold $(R \times S, g)$ is denoted by $R \times_\psi S$. If U_1 is the tangent vector field to $M = R \times_\psi S$ at (p, q) then

$$\|U_1\|^2 = \|d\pi_1 U_1\|^2 + \psi^2(p) \|d\pi_2 U_1\|^2. \quad (2.16)$$

We have the following theorem,

Theorem 2.3. [17]. Let $M = R \times_\psi S$ be the warped product manifolds. If $X_1, Y_1 \in TR$ and $V_1, W_1 \in TS$ then

$$(i) \quad \nabla_{X_1} Y_1 \in TR,$$

$$(ii) \quad \nabla_{X_1} V_1 = \nabla_{V_1} X_1 = \left(\frac{X_1 \psi}{\psi}\right) V_1,$$

$$(iii) \quad \nabla_{V_1} W_1 = \frac{-g(V_1, W_1)}{\psi} \nabla \psi.$$

From the above theorem, for the warped product $M = R \times_\psi S$, it is easy to observe that

$$\nabla_{X_1} V_1 = \nabla_{V_1} X_1 = (X_1 \ln \psi) V_1, \quad (2.17)$$

for any $X_1 \in TR$ and $V_1 \in TS$.

$\nabla \psi$ is the gradient of ψ and is expressed by

$$g(\nabla \psi, U_1) = U_1 \psi, \quad (2.18)$$

for all $U_1 \in TM$.

If the warping function ψ is constant, then the warped product is said to be trivial warped product.

Let M be a m -dimensional Riemannian manifold with Riemannian metric g and let $\{u_1, \dots, u_m\}$ be an orthonormal basis of TM . As a significance of (2.18), we have

$$\|\nabla \psi\|^2 = \sum_{i=1}^m (u_i(\psi))^2 \quad (2.19)$$

The Laplacian of ψ is given by

$$\Delta \psi = \sum_{i=1}^m \{(\nabla_{u_i} u_i) \psi - u_i u_i \psi\}. \quad (2.20)$$

Now, we state the Hopf's Lemma.

Lemma 2.1. [3]. If ψ is a differentiable function on a n -dimensional compact Riemannian manifold. If $\Delta \psi \geq 0$ or $\Delta \psi \leq 0$ everywhere on M , then ψ is a constant function.

3. Results and Discussion

This section deal with the study of the contact CR-warped product submanifolds of a nearly cosymplectic manifold and is divided into the two subsections.

3.1 Inequalities of the first kind

In this subsection, some characterizing inequalities are proved for existence of these types of warped product submanifolds.

Theorem 3.1. [18]. *A warped product submanifold $M = N_1 \times_\psi N_2$ of a nearly cosymplectic manifold \bar{M} is simply a Riemannian product if the structure vector field ξ_1 is tangent to N_2 , where N_1 and N_2 are the Riemannian manifolds.*

Throughout this paper, we consider the warped products of the type $M = N^T \times_\psi N^\perp$, such that N^T is an invariant submanifold of \bar{M} tangent to ξ_1 and N^\perp is an anti-invariant submanifold of \bar{M} . These types of warped product submanifolds are called the contact CR-warped product submanifolds. Now we have the following basic results for further application.

Lemma 3.1. [18]. *Let $M = N^T \times_\psi N^\perp$ be a contact CR-warped product submanifold of a nearly cosymplectic manifold \bar{M} , then we have*

- (i) $\xi_1 \ln \psi = 0$,
- (ii) $g(\sigma(U_1, V_1), \phi W_1) = 0$,
- (iii) $g(\sigma(\phi U_1, W_1), \phi W_1) = U_1 \ln \psi \|W_1\|^2$,

for any $U_1 \in TN^T$ and $W_1 \in TN^\perp$.

The following Lemma will be utilized for subsequent results.

Lemma 3.2. *Let $M = N^T \times_\psi N^\perp$ be a contact CR-warped product submanifold of a nearly cosymplectic manifold \bar{M} , then we have*

$$g(\sigma(\phi U_1, W_1), \phi \sigma(U_1, W_1)) = \|\sigma_\mu(U_1, W_1)\|^2 - g(\phi \sigma(U_1, W_1), Q_{U_1} W_1),$$

for any $U_1 \in TN^T$ and $W_1 \in TN^\perp$.

Proof. By (2.5) and (2.9)

$$\sigma(\phi U_1, W_1) = (\bar{\nabla}_{W_1} \phi) U_1 + \phi \nabla_{W_1} U_1 + \phi \sigma(U_1, W_1) - \nabla_{W_1} \phi U_1.$$

Thus by using (2.12) and (2.17)

$$\sigma(\phi U_1, W_1) = P_{W_1} U_1 + Q_{W_1} U_1 + U_1 \ln \psi \phi W_1 + \phi \sigma(U_1, W_1) - \phi U_1 \ln \psi W_1.$$

Comparing the normal parts

$$\sigma(\phi U_1, W_1) = Q_{W_1} U_1 + U_1 \ln \psi \phi W_1 + \phi \sigma_\mu(U_1, W_1),$$

or

$$g(\sigma(\phi U_1, W_1), \phi \sigma(U_1, W_1)) = g(Q_{W_1} U_1, \phi \sigma(U_1, W_1)) + \|\sigma_\mu(U_1, W_1)\|^2.$$

By using (2.13)(b), we get

$$g(\sigma(\phi U_1, W_1), \phi\sigma(U_1, W_1)) = \|\sigma_\mu(U_1, W_1)\|^2 - g(\phi\sigma(U_1, W_1), Q_{U_1}W_1).$$

□

Further, we have the following characterizing inequalities for the contact CR-warped product submanifolds of a generalized Sasakian space form admitting a nearly cosymplectic structure.

Theorem 3.2. *Let $M = N^T \times_\psi N^\perp$ be a contact CR-warped product submanifold of a generalized Sasakian space form $\bar{M}(f_1, f_2, f_3)$ admitting a nearly cosymplectic structure such that M^T is a compact submanifold. Then, M is a contact CR-product submanifold if either one of the following inequality holds*

$$(i) \sum_{i=1}^{2k_1} \sum_{j=1}^{k_2} \|\sigma_\mu(u_i, u^j)\|^2 \geq 2.k_1.k_2.f_2 + \sum_{i=1}^{2k_1} \sum_{j=1}^{k_2} \|Q_{u_i}u^j\|^2,$$

$$(ii) \sum_{i=1}^{2k_1} \sum_{j=1}^{k_2} \|\sigma_\mu(u_i, u^j)\|^2 \leq 2.k_1.k_2.f_2,$$

where σ_μ is the component of σ in μ , $2k_1 + 1$ and k_2 are the dimensions of M^T and M^\perp respectively.

Proof. For any unit vector fields $U_1 \in TN^T - \langle \xi_1 \rangle$ and $W_1 \in TN^\perp$. Then from (2.4) we have

$$\bar{R}(U_1, \phi U_1, W_1, \phi W_1) = -2.f_2.g(U_1, U_1) g(W_1, W_1). \quad (3.1)$$

By Codazzi equation, we calculate the curvature as follows

$$\begin{aligned} \bar{R}(U_1, \phi U_1, W_1, \phi W_1) &= g(\nabla_{U_1}^\perp \sigma(\phi U_1, W_1), \phi W_1) - g(\sigma(\nabla_{U_1} \phi U_1, W_1), \phi W_1) - \\ &\quad - g(\sigma(\phi U_1, \nabla_{U_1} W_1), \phi W_1) - g(\nabla_{\phi U_1}^\perp \sigma(U_1, W_1), \phi W_1) + \\ &\quad + g(\sigma(\nabla_{\phi U_1} U_1, W_1), \phi W_1) + g(\sigma(U_1, \nabla_{\phi U_1} W_1), \phi W_1). \end{aligned} \quad (3.2)$$

By using part (iii) of the Lemma 3.1, (2.9), (2.5) and (2.12), we get

$$\begin{aligned} g(\nabla_{U_1}^\perp \sigma(\phi U_1, W_1), \phi W_1) &= U_1 g(\sigma(\phi U_1, W_1), \phi W_1) - g(\sigma(\phi U_1, W_1), \bar{\nabla}_{U_1} \phi W_1) \\ &= U_1 (U_1 \ln \psi g(W_1, W_1)) - g(\sigma(\phi U_1, W_1), (\bar{\nabla}_{U_1} \phi) W_1 + \phi \bar{\nabla}_{U_1} W_1). \end{aligned}$$

On further simplification the above equation yields

$$\begin{aligned} g(\nabla_{U_1}^\perp \sigma(\phi U_1, W_1), \phi W_1) &= U_1^2 \ln \psi g(W_1, W_1) + 2(U_1 \ln \psi)^2 g(W_1, W_1) \\ &\quad - g(\sigma(\phi U_1, W_1), Q_{U_1} W_1) \\ &\quad - g(\sigma(\phi U_1, W_1), \phi\sigma(U_1, W_1)) \\ &\quad - U_1 \ln \psi g(\sigma(\phi U_1, W_1), \phi W_1). \end{aligned}$$

By using the Lemma 3.2, we have

$$\begin{aligned} g(\nabla_{U_1}^\perp \sigma(\phi U_1, W_1), \phi W_1) &= U_1^2 \ln \psi g(W_1, W_1) + (U_1 \ln \psi)^2 g(W_1, W_1) - \|\sigma_\mu(U_1, W_1)\|^2 \\ &\quad - g(\phi\sigma(U_1, W_1) - \sigma(\phi U_1, W_1), Q_{U_1} W_1). \end{aligned}$$

Further, using (2.5), (2.12), (2.13)(b) and (2.17) in the last term of the above equation, we get

$$\begin{aligned} g(\nabla_{U_1}^\perp \sigma(\phi U_1, W_1), \phi W_1) &= U_1^2 \ln \psi g(W_1, W_1) + (U_1 \ln \psi)^2 g(W_1, W_1) \\ &\quad - \|\sigma_\mu(U_1, W_1)\|^2 + \|Q_{U_1} W_1\|^2. \end{aligned} \quad (3.3)$$

Similarly, we can calculate

$$\begin{aligned} -g(\nabla_{\phi U_1}^\perp \sigma(U_1, W_1), \phi W_1) &= (\phi U_1)^2 \ln \psi g(W_1, W_1) + (\phi U_1 \ln \psi)^2 g(W_1, W_1) \\ &\quad - \|\sigma_\mu(\phi U_1, W_1)\|^2 + \|Q_{\phi U_1} W_1\|^2. \end{aligned} \quad (3.4)$$

From part (iii) of the Lemma 3.1, we have

$$g(A_{\phi W_1} W_1, \phi U_1) = U_1 \ln \psi,$$

replacing U_1 by $\nabla_{U_1} U_1$

$$g(A_{\phi W_1} W_1, \phi \nabla_{U_1} U_1) = \nabla_{U_1} U_1 \ln \psi.$$

By utilising (2.5) in the last equation, we acquire

$$g(A_{\phi W_1} W_1, \phi(\bar{\nabla}_{U_1} U_1 - \sigma(U_1, U_1))) = \nabla_{U_1} U_1 \ln \psi. \quad (3.5)$$

By use of (2.5), (2.9), (2.3) and (2.17), it is easy to see that $\sigma(U_1, U_1) \in \mu$, applying this fact in (3.5), then we get

$$g(A_{\phi W_1} W_1, \bar{\nabla}_{U_1} \phi U_1 - (\bar{\nabla}_{U_1} \phi) U_1) = \nabla_{U_1} U_1 \ln \psi.$$

By (2.3) and (2.5), the previous equation transformed to

$$g(A_{\phi W_1} W_1, \nabla_{U_1} \phi U_1) = \nabla_{U_1} U_1 \ln \psi.$$

or

$$g(\sigma(\nabla_{U_1} \phi U_1, W_1), \phi W_1) = \nabla_{U_1} U_1 \ln \psi \quad (3.6)$$

Similarly,

$$g(\sigma(\nabla_{\phi U_1} U_1, W_1), \phi W_1) = -\nabla_{\phi U_1} \phi U_1 \ln \psi. \quad (3.7)$$

By use of (2.17) and the part (iii) of the Lemma 3.1, it is simple to see the following

$$g(\sigma(\phi U_1, \nabla_{U_1} W_1), \phi W_1) = (U_1 \ln \psi)^2 g(W_1, W_1) \quad (3.8)$$

and

$$g(\sigma(U_1, \nabla_{\phi U_1} W_1), \phi W_1) = -(\phi U_1 \ln \psi)^2 g(W_1, W_1). \quad (3.9)$$

Substituting (3.3), (3.4), (3.6), (3.7), (3.8) and (3.9) in (3.2), we find

$$\begin{aligned} \bar{R}(U_1, \phi U_1, W_1, \phi W_1) &= U_1^2 \ln \psi g(W_1, W_1) + (\phi U_1)^2 \ln \psi g(W_1, W_1) \\ &\quad - \nabla_{U_1} U_1 \ln \psi g(W_1, W_1) - \nabla_{\phi U_1} \phi U_1 g(W_1, W_1) \\ &\quad - \|\sigma_\mu(U_1, W_1)\|^2 - \|\sigma_\mu(\phi U_1, W_1)\|^2 + \|Q_{U_1} W_1\|^2 \\ &\quad + \|Q_{\phi U_1} W_1\|^2. \end{aligned} \quad (3.10)$$

Let

$$\begin{aligned} \{u_0 &= \xi_1, u_1, u_2, \dots, u_{k_1}, u_{k_1+1} = \phi u_1, \\ &u_{k_1+2} = \phi u_2, \dots, u_{2k_1} = \phi u_{k_1}, u^1, u^2, \dots, u^{k_2}\} \end{aligned}$$

be an orthonormal frame of TM such that the set of the vector fields

$$\{u_1, u_2, \dots, u_{k_1}, \phi u_1, \phi u_2, \dots, \phi u_{k_1}\}$$

is tangent to M_T and $\{u^1, u^2, \dots, u^{k_2}\}$ is tangent to M_\perp .

Using (3.1) and (2.20) in (3.10) and summing over $i = 1, 2, \dots, k_1$ and $j = 1, 2, \dots, k_2$, we get

$$k_2 \Delta \ln \psi = 2.k_1.k_2.f_2 - \sum_{i=1}^{2k_1} \sum_{j=1}^{k_2} \|\sigma_\mu(u_i, u^j)\|^2 + \sum_{i=1}^{2k_1} \sum_{j=1}^{k_2} \|Q_{u_i} u^j\|^2. \quad (3.11)$$

From Hopf's Lemma and (3.11), if

$$\sum_{i=1}^{2k_1} \sum_{j=1}^{k_2} \|\sigma_\mu(u_i, u^j)\|^2 \geq 2.k_1.k_2.f_2 + \sum_{i=1}^{2k_1} \|Q_{u_i} u^j\|^2,$$

or

$$\sum_{i=1}^{2k_1} \sum_{j=1}^{k_2} \|\sigma_\mu(u_i, u^j)\|^2 \leq 2.k_1.k_2.f_2,$$

then the warping function ψ is constant on M i.e., M is simply a contact CR-product submanifold, which proves the theorem completely.

□

From the above observations, we have the following propositions, which can be confirmed easily.

Proposition 3.1. *Let $M = N^T \times_\psi N^\perp$ be a contact CR-warped product submanifold of a generalized Sasakian space form $\bar{M}(f_1, f_2, f_3)$ admitting a nearly cosymplectic structure such that M^T is a compact submanifold. Then M is contact CR-product if and only if*

$$\sum_{i=1}^{2k_1} \sum_{j=1}^{k_2} \|\sigma_\mu(u_i, u^j)\|^2 = 2.k_1.k_2.f_2 + \sum_{i=1}^{2k_1} \sum_{j=1}^{k_2} \|Q_{u_i} u^j\|^2.$$

Moreover, as a special case, from Theorem 3.2, we derive the following result.

Theorem 3.3. *Let $M = N^T \times_\psi N^\perp$ be a contact CR-warped product submanifold of a cosymplectic space form $\bar{M}(c)$ such that M^T is compact. Then M is a contact CR-product submanifold if either the inequality*

$$\sum_{i=1}^{2k_1} \sum_{j=1}^{k_2} \|\sigma_\mu(u_i, u^j)\|^2 \geq \frac{c.k_1.k_2}{2},$$

or

$$\sum_{i=1}^{2k_1} \sum_{j=1}^{k_2} \|\sigma_\mu(u_i, u^j)\|^2 \leq \frac{c.k_1.k_2}{2}$$

holds, where σ_μ denotes the component of σ in μ , $2k_1 + 1$ and k_2 are the dimensions of M^T and M^\perp .

Corollary 3.4. *Let $M = N^T \times_\psi N^\perp$ be a compact contact CR-warped product submanifold of a cosymplectic space form $\bar{M}(c)$. Then M is a contact CR-product submanifold if and only if*

$$\sum_{i=1}^{2k_1} \sum_{j=1}^{k_2} \|\sigma_\mu(u_i, u^j)\|^2 = \frac{c.k_1.k_2}{2}.$$

3.2 Inequalities of the second kind

In the present subsection, we prove an approximation for the norm of the second fundamental form

Theorem 3.5. *Let $\bar{M}(f_1, f_2, f_3)$ be a $(2n + 1)$ -dimensional generalized Sasakian space form admitting a nearly cosymplectic structure and $M = N^T \times_{\psi} N^{\perp}$ be an m -dimensional contact CR-warped product submanifold, such that M^T is a $(2k_1 + 1)$ -dimensional invariant submanifold tangent to ξ_1 and M^{\perp} be a k_2 -dimensional anti-invariant submanifold of $\bar{M}(f_1, f_2, f_3)$. Then*

(i) *The squared norm of the second fundamental form σ satisfies*

$$\|\sigma\|^2 \geq k_2\{\|\nabla \ln \psi\|^2 - \Delta \ln \psi\} + 2.k_1.k_2.f_2 + \|Q_D D^{\perp}\|^2, \quad (3.12)$$

where Δ denotes the Laplace operator on M^T .

(ii) *The equality sign of (3.12) holds identically if and only if we have*

(a) *M^T is a totally geodesic invariant submanifold of $\bar{M}(f_1, f_2, f_3)$. Hence N^T is a generalized Sasakian space form admitting a nearly cosymplectic structure.*

(b) *M^{\perp} is a totally umbilical anti-invariant submanifold of $\bar{M}(f_1, f_2, f_3)$.*

Proof. For any $U_1 \in TN^T$ and $W_1 \in TN^{\perp}$, from (2.8), (2.6) and (2.3) we have

$$g(\sigma(\xi_1, W_1), \phi W_1) = 0$$

and from part (iii) of the Lemma 3.1

$$g(\sigma(\phi U_1, W_1), \phi W_1) = U_1 \ln \psi \|W_1\|^2.$$

From above two equations one can get

$$\sum_{i=0}^{2k_1} \sum_{j=1}^{k_2} \|\sigma_{\phi D^{\perp}}(u_i, u^j)\|^2 = k_2 \|\nabla \ln \psi\|^2. \quad (3.13)$$

Again from equation (3.11)

$$\sum_{i=1}^{2k_1} \sum_{j=1}^{k_2} \|\sigma_{\mu}(u_i, u^j)\|^2 = 2.k_1.k_2.f_2 - k_2 \Delta \ln \psi + \sum_{i=1}^{2k_1} \sum_{j=1}^{k_2} \|Q_{u_i} u^j\|^2. \quad (3.14)$$

The following notation is assumed

$$\sum_{i=1}^{2k_1} \sum_{j=1}^{k_2} \|Q_{u_i} u^j\|^2 = \|Q_D D^{\perp}\|^2.$$

Utilizing the above notation in (3.14) and combining it with (3.13), we obtain the inequality (3.12).

Let σ'' be the second fundamental form of M^{\perp} in M . Then, for any $U_1 \in TN^T$ and $Z_1, \bar{Z}_1 \in TN^{\perp}$, we have

$$g(\sigma''(Z_1, \bar{Z}_1), U_1) = g(\nabla_{Z_1} \bar{Z}_1, U_1) = -U_1 \ln \psi g(Z_1, \bar{Z}_1),$$

By using (2.18), we get

$$\sigma''(Z_1, \bar{Z}_1) = -g(Z_1, \bar{Z}_1) \nabla \ln \psi. \quad (3.15)$$

If the equality sign of (3.12) holds identically, then we get

$$\sigma(D, D) = 0, \quad \sigma(D^{\perp}, D^{\perp}) = 0. \quad (3.16)$$

The first case of (3.16) implies that M^T is totally geodesic in M . On the other hand, one has

$$g(\sigma(U_1, \phi V_1), \phi W_1) = g(\bar{\nabla}_{U_1} \phi V_1, \phi W_1) = -g(\phi V_1, (\bar{\nabla}_{U_1} \phi) W_1). \quad (3.17)$$

By use of (2.9) and (2.5) we get the following equation

$$g(\phi V_1, (\bar{\nabla}_{W_1} \phi) U_1) = g(\phi V_1, \nabla_{W_1} \phi U_1) - g(V_1, \nabla_{W_1} U_1),$$

in view of (2.17) the previous equation reduced to

$$g(\phi V_1, (\bar{\nabla}_{W_1} \phi) U_1) = 0. \quad (3.18)$$

From (3.17), (3.18) and (2.3) we have

$$g(\sigma(U_1, \phi V_1), \phi W_1) = -g(\phi V_1, (\bar{\nabla}_{U_1} \phi) W_1) + (\bar{\nabla}_{W_1} \phi) U_1 = 0. \quad (3.19)$$

From (3.19), it is evident that the submanifold N^T is totally geodesic in $\bar{M}(f_1, f_2, f_3)$ and hence is a generalized Sasakian space form admitting a nearly cosymplectic structure.

The second case of (3.16) and (3.15) imply that the submanifold M^\perp is totally umbilical in $\bar{M}(f_1, f_2, f_3)$.

□

In the last we have the following Corollary, which can be deduced from inequality (3.12)

Corollary 3.6. *Let $M = N^T \times_\psi N_\perp$ be a contact CR-warped product submanifold of a cosymplectic space form $\bar{M}(c)$, then the squared norm of the second fundamental form satisfies*

$$\|\sigma\|^2 \geq k_2 \{ \|\nabla \ln \psi\|^2 - \Delta \ln \psi \} + \frac{c \cdot k_1 \cdot k_2}{2},$$

where Δ is the Laplace operator on M^T , and $2k_1+1$ and k_2 are the dimensions of M^T and M^\perp respectively.

Note 3.1. The inequality obtained in Corollary 2 is the improved version of the inequality obtained in [15].

4. Conclusion

The inequality $\sum_{i=1}^{k_1} \sum_{j=1}^{k_2} \|\sigma_\mu(u_i, w^j)\|^2 \geq \frac{c \cdot k_1 \cdot k_2}{4}$ for the existence of a contact CR-warped product submanifold in a cosymplectic space form $\bar{M}(c)$ was proved by M. Atceken [14]. In the Theorem 3.3, the first inequality is equivalent to the inequality obtained by M. Atceken and we also prove the second inequality for the contact CR-warped product submanifolds of a cosymplectic space form. Moreover, the inequalities obtained in Theorem 3.2 are the generalization of the inequalities that have obtained by M. Atceken [14]. On the other hand various estimate for the squared norm of the second fundamental form for the contact CR-warped product submanifolds in the background of Sasakian and Kenmotsu space forms are studied (see [11], [12]), still these types of estimate are not studied in the setting of the cosymplectic space forms as well as in the generalized Sasakian space forms admitting a nearly cosymplectic structure. So the present author tries to fill this gap and in this connection proved an optimal inequality for the squared norm of the second fundamental form in the setting of generalized Sasakian space forms admitting a nearly cosymplectic structure and in particular for the cosymplectic space forms.

5. Declarations

Competing Interests: The author declares that he has no competing interests.

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