



## Derivatives with Respect to Horizontal and Vertical Lifts of the Deformed Complete Lift Metric $\tilde{G}_f$ on Tangent Bundle

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ABSTRACT: In this paper, we define the deformed complete lift metric  $\tilde{G}_f$  on tangent bundle, which is completely determined by its action on vector fields of type  $X^H$  and  $\omega^V$ . Later, we obtain the covariant and Lie derivatives applied to the deformed complete lift metric  $\tilde{G}_f$  with respect to the horizontal and vertical lifts of vector fields, respectively.

Key Words: Covariant derivative, Lie derivative, Ddeformed complete lift metric  $\tilde{G}_f$ , Horizontal Lift, Vertical lift, Tangent bundle.

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### 1. Introduction

Let  $M$  be an  $n$ -dimensional Riemannian manifold with a Riemannian metric  $g$  and denote by  $\pi : TM \rightarrow M$  its tangent bundle with fiber the tangent spaces to  $M$ .  $TM$  is then a  $2n$ -dimensional smooth manifold and some local charts induced naturally from local charts on  $M$  may be used. Namely, a system of local coordinates  $(U, x^i)$  in  $M$  induces on  $TM$  a system of local coordinates  $(\pi^{-1}(U), x^i, x^{\bar{i}} = y^i)$ , where  $(x^i)$ ,  $i = 1, \dots, n$  is a local coordinate system defined in the neighborhood  $U$  and  $(y^i)$  is the Cartesian coordinates in each tangent space  $T_P M$  at an arbitrary point  $P$  in  $U$  with respect to the natural basis  $\{\frac{\partial}{\partial x^i} | P\}$ . Summation over repeated indices is always implied. The Riemannian manifolds and the tangent bundles studied a lot of authors [1,2,7,8] too.

Let  $X = X^i \frac{\partial}{\partial x^i}$  be the local expressions in  $U$  of a vector field  $X$  on  $M$ . The vertical lift  $X^V$ , the horizontal lift  $X^H$ , and the complete lift  $X^C$  of  $X$  are then given respectively by [6]

$$X^V = X^i \partial_{\bar{i}} \tag{1.1}$$

$$X^H = X^i \partial_i - y^j \Gamma_{jk}^i X^k \partial_{\bar{i}} \tag{1.2}$$

and

$$X^C = X^i \partial_i + y^j \partial_j X^i \partial_{\bar{i}} \tag{1.3}$$

with respect to the induced coordinates, where  $\partial_i = \frac{\partial}{\partial x^i}$ ,  $\partial_{\bar{i}} = \frac{\partial}{\partial y^i}$  and  $\Gamma_{jk}^i$  are the coefficients of the Levi-Civita connection  $\nabla$  of  $g$ .

Given a  $(p, q)$ -tensor field  $S$  on  $M$ ,  $q > 1$ , we then consider a tensor field  $\gamma S \in \mathfrak{S}_{q-1}^p(TM)$  on  $\pi^{-1}(U)$  by

$$\gamma S = (y^s S_{s i_2 \dots i_q}^{j_1 \dots j_p}) \frac{\partial}{\partial x^{j_1}} \otimes \dots \otimes \frac{\partial}{\partial x^{j_p}} \otimes dx^{i_2} \otimes \dots \otimes dx^{i_q}$$

with respect to the induced coordinates  $(x^i, y^i)$  ([11], p.12).

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2010 *Mathematics Subject Classification*: 15A72, 53A45, 47B47, 53C15.

Submitted November 30, 2010. Published April 21, 2020

### 1.1. The deformed complete lift metric $\tilde{G}_f$

In this section, we give the Levi-Civita connection  $\tilde{\nabla}$  of the tangent bundle  $TM$  with the deformed complete lift metric  $\tilde{G}_f$  and study fiber-preserving Killing vector fields on  $TM$ . The deformed complete lift metric  $\tilde{G}_f$  is defined by [6]

$$\begin{aligned}\tilde{G}(X^H, Y^H) &= fg(X, Y) \\ \tilde{G}(X^H, Y^V) &= \tilde{G}(X^V, Y^H) = g(X, Y) \\ \tilde{G}(X^V, Y^V) &= 0\end{aligned}\tag{1.4}$$

for all  $X, Y \in \mathfrak{S}_0^1(M)$ . We now give expressions of the deformed complete lift metric  $\tilde{G}_f$  and its inverse  $\tilde{G}_f^{-1}$  with respect to the adapted frame  $\{E_\beta\}$ :

$$\tilde{G}_f = \begin{pmatrix} fg_{ij} & g_{ij} \\ g_{ij} & 0 \end{pmatrix} \text{ and } \tilde{G}_f^{-1} = \begin{pmatrix} 0 & g^{jh} \\ g^{jh} & -fg^{jh} \end{pmatrix}$$

for all vector fields  $X$  and  $Y$  on  $M$ , and  $f > 0$ ,  $f \in C^\infty(M)$  [6]. For  $f = 1$ , it follows that  $\tilde{g} =^S g$ , i.e. the metric  $\tilde{g}$  is generalization of Sasakian metric  $^Sg$  [10].

Determining both the deformed complete metric  $\tilde{G}_f$  and the almost complex structure  $J^H$ , and using the facts  $X^V(fg(Y, Z)) = 0$  and  $X^H(fg(Y, Z)) = X(f)g(Y, Z) + fX(g(Y, Z))$ , we calculate

## 2. Main Results

**Definition 2.1.** Let  $M$  be an  $n$ -dimensional differentiable manifold. Differential transformation  $D = L_X$  is called as Lie derivation with respect to vector field  $X \in \mathfrak{S}_0^1(M)$  if

$$\begin{aligned}L_X f &= Xf, \forall f \in \mathfrak{S}_0^0(M^n), \\ L_X Y &= [X, Y], \forall X, Y \in \mathfrak{S}_0^1(M^n).\end{aligned}\tag{2.1}$$

$[X, Y]$  is called by Lie bracketed. The Lie derivative  $L_X F$  of a tensor field  $F$  of type  $(1, 1)$  with respect to a vector field  $X$  is defined by [3, 4, 11]

$$(L_X F)Y = [X, FY] - F[X, Y].\tag{2.2}$$

**Definition 2.2.** The bracket operation of vertical and horizontal vector fields is given by the following formulas:

$$\begin{aligned}[X^H, Y^H] &= [X, Y]^H - (R(X, Y)u)^V \\ [X^H, Y^V] &= (\nabla_X Y)^V \\ [X^V, Y^V] &= 0, \quad X^H f^V = (Xf)^V\end{aligned}\tag{2.3}$$

for all  $X, Y \in \mathfrak{S}_0^1(M)$ ,  $f \in \mathfrak{S}_0^0(M)$  [5], where  $R$  is the Riemannian curvature of  $g$  defined by

$$R(X, Y) = [\nabla_X, \nabla_Y] - \nabla_{[X, Y]}.$$

**Theorem 2.3.** Let  $\tilde{G}_f$  be the deformed complete lift metric, is defined by (1.4) and  $L_X$  the operator Lie derivation with respect to  $X$ . From (1.4), Definition (2.1) and Definition (2.2), we get the following results

- i)  $(L_{X^V} \tilde{G}_f)(Y^V, Z^V) = 0$ ,
- ii)  $(L_{X^V} \tilde{G}_f)(Y^V, Z^H) = 0$ ,
- iii)  $(L_{X^V} \tilde{G}_f)(Y^H, Z^V) = 0$ ,
- iv)  $(L_{X^H} \tilde{G}_f)(Y^V, Z^V) = 0$ ,
- v)  $(L_{X^H} \tilde{G}_f)(Y^H, Z^V) = (L_X g)(Y, Z) - g(Y, (\nabla_Z X))$ ,
- vi)  $(L_{X^V} \tilde{G}_f)(Y^H, Z^H) = g((\hat{\nabla}_Y X), Z) + g(Y, (\hat{\nabla}_Z X))$ ,
- vii)  $(L_{X^H} \tilde{G}_f)(Y^V, Z^H) = (L_X g)(Y, Z) - g((\nabla_Y X), Z)$ ,
- viii)  $(L_{X^H} \tilde{G}_f)(Y^H, Z^H) = (L_X fg)(Y, Z) + g((R(X, Y)U, Z) + g(Y, (R(X, Z)U))$ ,

where the vertical, horizontal and complete lifts  $X^V, X^H, X^C, \in \mathfrak{S}_0^1(TM)$  of  $X \in \mathfrak{S}_0^1(M)$ , defined by (1.1), (1.2), (1.3), respectively.

*Proof.* i)

$$\begin{aligned} (L_{X^V} \tilde{G}_f)(Y^V, Z^V) &= L_{X^V} \tilde{G}_f(Y^V, Z^V) - \tilde{G}_f(L_{X^V} Y^V, Z^V) - \tilde{G}_f(Y^V, L_{X^V} Z^V) \\ &= L_{X^V} \tilde{G}_f(Y^V, Z^V) \\ &= 0 \end{aligned}$$

ii)

$$\begin{aligned} (L_{X^V} \tilde{G}_f)(Y^V, Z^H) &= L_{X^V} \tilde{G}_f(Y^V, Z^H) - \tilde{G}_f(L_{X^V} Y^V, Z^H) - \tilde{G}_f(Y^V, L_{X^V} Z^H) \\ &= X^V g(Y, Z) - \tilde{G}_f(Y^V, [X, Z]^V - (\nabla_X Z)^V) \\ &= -\tilde{G}_f(Y^V, [X, Z]^V) + \tilde{G}_f(Y^V, (\nabla_X Z)^V) \\ &= 0 \end{aligned}$$

iii)

$$\begin{aligned} (L_{X^V} \tilde{G}_f)(Y^H, Z^V) &= L_{X^V} \tilde{G}_f(Y^H, Z^V) - \tilde{G}_f(L_{X^V} Y^H, Z^V) - \tilde{G}_f(Y^H, L_{X^V} Z^V) \\ &= X^V g(Y, Z) - \tilde{G}_f([X, Y]^V - (\nabla_X Y)^V, Z^V) \\ &= -\tilde{G}_f([X, Y]^V, Z^V) + \tilde{G}_f((\nabla_X Y)^V, Z^V) \\ &= 0 \end{aligned}$$

iv)

$$\begin{aligned} (L_{X^H} \tilde{G}_f)(Y^V, Z^V) &= L_{X^H} \tilde{G}_f(Y^V, Z^V) - \tilde{G}_f(L_{X^H} Y^V, Z^V) - \tilde{G}_f(Y^V, L_{X^H} Z^V) \\ &= -\tilde{G}_f((\hat{\nabla}_X Y)^V, Z^V) - \tilde{G}_f(Y^V, (\hat{\nabla}_X Z)^V) \\ &= 0 \end{aligned}$$

v)

$$\begin{aligned} (L_{X^H} \tilde{G}_f)(Y^H, Z^V) &= L_{X^H} \tilde{G}_f(Y^H, Z^V) - \tilde{G}_f(L_{X^H} Y^H, Z^V) - \tilde{G}_f(Y^H, L_{X^H} Z^V) \\ &= Xg(Y, Z) - \tilde{G}_f([X, Y]^H - (R(X, Y)U)^V, Z^V) \\ &\quad - \tilde{G}_f(Y^H, [X, Z]^V + (\nabla_Z X)^V) \\ &= Xg(Y, Z) - g([X, Y], Z) - g(Y, [X, Z]) - g(Y, (\nabla_Z X)) \\ &= (L_X g)(Y, Z) - g(Y, (\nabla_Z X)) \end{aligned}$$

vi)

$$\begin{aligned} (L_{X^V} \tilde{G}_f)(Y^H, Z^H) &= L_{X^V} \tilde{G}_f(Y^H, Z^H) - \tilde{G}_f(L_{X^V} Y^H, Z^H) - \tilde{G}_f(Y^H, L_{X^V} Z^H) \\ &= X^V (fg(Y, Z)) - \tilde{G}_f([X, Y]^V - (\nabla_X Y)^V, Z^H) \\ &\quad - \tilde{G}_f(Y^H, [X, Z]^V - (\nabla_X Z)^V) \\ &= -\tilde{G}_f([X, Y]^V, Z^H) + \tilde{G}_f((\nabla_X Y)^V, Z^H) - \tilde{G}_f(Y^H, [X, Z]^V) \\ &\quad + \tilde{G}_f(Y^H, (\nabla_X Z)^V) \\ &= g(-[X, Y] + (\nabla_X Y), Z) + g(Y, -[X, Z] + (\nabla_X Z)) \\ &= g([Y, X] + (\nabla_X Y), Z) + g(Y, [Z, X] + (\nabla_X Z)) \\ &= g((\hat{\nabla}_Y X), Z) + g(Y, (\hat{\nabla}_Z X)) \end{aligned}$$

vii)

$$\begin{aligned}
(L_{X^H}\tilde{G}_f)(Y^V, Z^H) &= L_{X^H}\tilde{G}_f(Y^V, Z^H) - \tilde{G}_f(L_{X^H}Y^V, Z^H) - \tilde{G}_f(Y^V, L_{X^H}Z^H) \\
&= X^H g(Y, Z) - \tilde{G}_f([X, Y]^V + (\nabla_X Y)^V, Z^H) \\
&\quad - \tilde{G}_f(Y^V, [X, Z]^H - (R(X, Z)U)^V) \\
&= Xg(Y, Z) - \tilde{G}_f([X, Y]^V, Z^H) - \tilde{G}_f((\nabla_Y X)^V, Z^H) \\
&\quad - \tilde{G}_f(Y^V, [X, Z]^H) + \tilde{G}_f(Y^V (R(X, Z)U)^V) \\
&= Xg(Y, Z) - g([X, Y], Z) - g((\nabla_Y X), Z) - g(Y, [X, Z]) \\
&= (L_X g)(Y, Z) - g((\nabla_Y X), Z)
\end{aligned}$$

viii)

$$\begin{aligned}
(L_{X^H}\tilde{G}_f)(Y^H, Z^H) &= L_{X^H}\tilde{G}_f(Y^H, Z^H) - \tilde{G}_f(L_{X^H}Y^H, Z^H) - \tilde{G}_f(Y^H, L_{X^H}Z^H) \\
&= X^H (fg(Y, Z)) - \tilde{G}_f([X, Y]^H - (R(X, Y)U)^V, Z^H) \\
&\quad - \tilde{G}_f(Y^H, [X, Z]^H - (R(X, Z)U)^V) \\
&= X(f)g(Y, Z) + fXg(Y, Z) - fg([X, Y], Z) + g((R(X, Y)U), Z) \\
&\quad - fg(Y, [X, Z]) + g(Y, (R(X, Z)U)) \\
&= (L_X fg)(Y, Z) + g((R(X, Y)U), Z) + g(Y, (R(X, Z)U))
\end{aligned}$$

□

**Definition 2.4.** *Differential transformation of algebra  $T(M)$ , deffined by*

$$D = \nabla_X : T(M) \rightarrow T(M), X \in \mathfrak{S}_0^1(M),$$

is called as covariant derivation with respect to vector field  $X$  if

$$\begin{aligned}
\nabla_{fX+gY}t &= f\nabla_X t + g\nabla_Y t, \\
\nabla_X f &= Xf,
\end{aligned} \tag{2.4}$$

where  $\forall f, g \in \mathfrak{S}_0^0(M), \forall X, Y \in \mathfrak{S}_0^1(M), \forall t \in \mathfrak{S}(M)$ .

On the other hand, a transformation deffined by

$$\nabla : \mathfrak{S}_0^1(M) \times \mathfrak{S}_0^1(M) \rightarrow \mathfrak{S}_0^1(M),$$

is called as affin connection [9,11]. In addition, the horizontal lift of an affine connection  $\nabla$  in  $M$  to  $T(M)$ , denoted by  $\nabla^H$ , defined by

$$\begin{aligned}
\nabla_{X^V}^H Y^V &= 0, \quad \nabla_{X^V}^H Y^H = 0, \\
\nabla_{X^H}^H Y^V &= (\nabla_X Y)^V, \quad \nabla_{X^H}^H Y^H = (\nabla_X Y)^H
\end{aligned} \tag{2.5}$$

for any  $X, Y \in \mathfrak{S}_0^1(M)$ .

**Theorem 2.5.** *Let  $\tilde{G}_f$  be the deformed complete lift metric, is defined by (1.4) and the horizontal lift  $\nabla^H$  of a symmetric affine connection  $\nabla$  in  $M$  to  $T(M)$ . From (1.4) and Definition 2.4, we get the following results*

$$\begin{aligned}
i) \quad (\nabla_{X^V}^H \tilde{G}_f)(Y^V, Z^V) &= 0, \\
ii) \quad (\nabla_{X^V}^H \tilde{G}_f)(Y^V, Z^H) &= 0, \\
iii) \quad (\nabla_{X^V}^H \tilde{G}_f)(Y^H, Z^V) &= 0, \\
iv) \quad (\nabla_{X^V}^H \tilde{G}_f)(Y^H, Z^H) &= 0, \\
v) \quad (\nabla_{X^H}^H \tilde{G}_f)(Y^V, Z^V) &= 0, \\
vi) \quad (\nabla_{X^H}^H \tilde{G}_f)(Y^V, Z^H) &= (\nabla_X g)(Y, Z), \\
vii) \quad (\nabla_{X^H}^H \tilde{G}_f)(Y^H, Z^V) &= (\nabla_X g)(Y, Z), \\
viii) \quad (\nabla_{X^H}^H \tilde{G}_f)(Y^H, Z^H) &= (\nabla_X fg)(Y, Z),
\end{aligned}$$

where the vertical, horizontal and complete lifts  $X^V, X^H, X^C, \in \mathfrak{S}_0^1(TM)$  of  $X \in \mathfrak{S}_0^1(M)$ , defined by (1.1), (1.2), (1.3), respectively.

*Proof. i)*

$$\begin{aligned} (\nabla_{X^V}^H \tilde{G}_f)(Y^V, Z^V) &= \nabla_{X^V}^H \tilde{G}_f(Y^V, Z^V) - \tilde{G}_f(\nabla_{X^V}^H Y^V, Z^V) - \tilde{G}_f(Y^V, \nabla_{X^V}^H Z^V) \\ &= X^V \tilde{G}_f(Y^V, Z^V) \\ &= 0 \end{aligned}$$

*ii)*

$$\begin{aligned} (\nabla_{X^V}^H \tilde{G}_f)(Y^V, Z^H) &= \nabla_{X^V}^H \tilde{G}_f(Y^V, Z^H) - \tilde{G}_f(\nabla_{X^V}^H Y^V, Z^H) - \tilde{G}_f(Y^V, \nabla_{X^V}^H Z^H) \\ &= X^V g(Y, Z) \\ &= 0 \end{aligned}$$

*iii)*

$$\begin{aligned} (\nabla_{X^V}^H \tilde{G}_f)(Y^H, Z^V) &= \nabla_{X^V}^H \tilde{G}_f(Y^H, Z^V) - \tilde{G}_f(\nabla_{X^V}^H Y^H, Z^V) - \tilde{G}_f(Y^H, \nabla_{X^V}^H Z^V) \\ &= X^V g(Y, Z) \\ &= 0 \end{aligned}$$

*iv)*

$$\begin{aligned} (\nabla_{X^V}^H \tilde{G}_f)(Y^H, Z^H) &= \nabla_{X^V}^H \tilde{G}_f(Y^H, Z^H) - \tilde{G}_f(\nabla_{X^V}^H Y^H, Z^H) - \tilde{G}_f(Y^H, \nabla_{X^V}^H Z^H) \\ &= X^V fg(Y, Z) \\ &= 0 \end{aligned}$$

*v)*

$$\begin{aligned} (\nabla_{X^H}^H \tilde{G}_f)(Y^V, Z^V) &= \nabla_{X^H}^H \tilde{G}_f(Y^V, Z^V) - \tilde{G}_f(\nabla_{X^H}^H Y^V, Z^V) - \tilde{G}_f(Y^V, \nabla_{X^H}^H Z^V) \\ &= -\tilde{G}_f((\nabla_X Y)^V, Z^V) - \tilde{G}_f(Y^V, (\nabla_X Z)^V) \\ &= 0 \end{aligned}$$

*vi)*

$$\begin{aligned} (\nabla_{X^H}^H \tilde{G}_f)(Y^V, Z^H) &= \nabla_{X^H}^H \tilde{G}_f(Y^V, Z^H) - \tilde{G}_f(\nabla_{X^H}^H Y^V, Z^H) - \tilde{G}_f(Y^V, \nabla_{X^H}^H Z^H) \\ &= Xg(Y, Z) - \tilde{G}_f((\nabla_X Y)^V, Z^H) - \tilde{G}_f(Y^V, (\nabla_X Z)^H) \\ &= Xg(Y, Z) - g((\nabla_X Y), Z) - g(Y, (\nabla_X Z)) \\ &= (\nabla_X g)(Y, Z) \end{aligned}$$

*vii)*

$$\begin{aligned} (\nabla_{X^H}^H \tilde{G}_f)(Y^H, Z^V) &= \nabla_{X^H}^H \tilde{G}_f(Y^H, Z^V) - \tilde{G}_f(\nabla_{X^H}^H Y^H, Z^V) - \tilde{G}_f(Y^H, \nabla_{X^H}^H Z^V) \\ &= Xg(Y, Z) - g((\nabla_X Y), Z) - g(Y, (\nabla_X Z)) \\ &= (\nabla_X g)(Y, Z) \end{aligned}$$

*viii)*

$$\begin{aligned} (\nabla_{X^H}^H \tilde{G}_f)(Y^H, Z^H) &= \nabla_{X^H}^H \tilde{G}_f(Y^H, Z^H) - \tilde{G}_f(\nabla_{X^H}^H Y^H, Z^H) - \tilde{G}_f(Y^H, \nabla_{X^H}^H Z^H) \\ &= X(f)g(Y, Z) + fXg(Y, Z) - \tilde{G}_f((\nabla_X Y)^H, Z^H) \\ &\quad - \tilde{G}_f(Y^H, (\nabla_X Z)^H) \\ &= X(f)g(Y, Z) + fXg(Y, Z) - fg((\nabla_X Y), Z) - g(Y, (\nabla_X Z)) \\ &= (\nabla_X fg)(Y, Z) \end{aligned}$$

□

### Acknowledgments

The authors are grateful to the referee for his/her valuable comments and suggestions.

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