



Some Common Fixed Point Theorems for Four Self-Mappings Satisfying a General Contractive Condition

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ABSTRACT: In the paper, we derive a general case for four weakly compatible self maps satisfying a general contractive condition due to the same method introduced by Altun et al. [2]. We make use of such a study to prove common fixed point theorems for weakly compatible maps along with *E.A.* and (*CLR*) properties.

Key Words: Common fixed point, Weakly compatible, *E.A.* property, (*CLR*) property.

Contents

1	Introduction	181
2	Main Results	182

1. Introduction

The study of common fixed point of mappings satisfying contractive conditions has been a very active field of research during recent years. The most general of the common fixed point theorems pertaining to four mappings A, B, S and T of a metric space (X, d) , uses either a Banach-type contractive condition [3] of the form

$$d(Ax, By) \leq km(x, y) \quad (0 \leq k < 1),$$

where

$$m(x, y) = \max\{d(Ax, By), d(Sx, Ax), d(Ty, By) \text{ and } \frac{1}{2}(d(Sx, By) + d(Ty, Ax))\},$$

or a Meir - Keeler - type (ε, δ) - contractive condition [6], that is, given $\varepsilon > 0$, there exists a $\delta > 0$ such that or a φ - contractive condition [7] of the form

$$d(Ax, By) \leq \varphi(m(x, y)),$$

involving a contractive gauge function $\varphi : [0, \infty) \rightarrow [0, \infty)$ such that $\varphi(t) < t$ for each $t > 0$. Note that Banach-type contractive condition is a special case of both conditions Meir - Keeler - type (ε, δ) - contractive and φ - contractive. A φ - contractive condition does not guarantee the existence of a fixed point unless some additional condition is assumed. Moreover, a φ - contractive condition, in general, does not imply the Meir - Keeler - type (ε, δ) - contractive condition. In the paper,

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we aim to prove a common fixed point theorem for four weakly compatible self - maps satisfying a general contractive condition and also prove common fixed point theorems for weakly compatible maps along with *E.A.* and (*CLR*) properties. We are now in a position to state the following three definitions which is an important to derive our main results.

Definition 1.1. [4] Two self maps f and g are said to be weakly compatible if they commute at coincidence points.

Definition 1.2. [1] Two self-mappings f and g of a metric space (X, d) are said to satisfy *E.A.* property if there exists a sequence $\{x_n\}$ in X such that $\lim_{n \rightarrow \infty} fx_n = \lim_{n \rightarrow \infty} gx_n = t$ for some t in X .

Definition 1.3. [8] Two self-mappings f and g of a metric space (X, d) are said to satisfy (*CLR**F*) property if there exists a sequence $\{x_n\}$ in X such that $\lim_{n \rightarrow \infty} fx_n = \lim_{n \rightarrow \infty} gx_n = fx$ for some x in X .

2. Main Results

Now, we give the following theorems.

Theorem 2.1. Let A, B, S and T be self maps of a metric space (X, d) satisfying the followings:

$$SX \subseteq BX, TX \subseteq AX, \quad (2.1)$$

for all $x \in X$, there exists right continuous functions $\psi, \phi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$, with

$$\begin{aligned} \psi(0) = 0 = \phi(0) \text{ and } \psi(s) < s \text{ for } s > 0 \text{ such that} \\ \psi(d(Sx, Ty)) \leq \psi(m(x, y)) - \phi(m(x, y)), \end{aligned} \quad (2.2)$$

where

$$m(x, y) = \max\{d(Ax, By), d(Sx, Ax), d(Ty, By), \frac{1}{2}(d(Sx, By) + d(Ty, Ax))\}.$$

If one of AX, BX, SX or TX is complete subspace of X , then the pair (A, S) or (B, T) have a coincidence point. Moreover, if pairs (A, S) and (B, T) are weakly compatible, then A, B, S and T have a unique common fixed point.

Proof: Let $x_0 \in X$ be an arbitrary point of X . from (2.1), we can construct a sequence $\{y_n\}$ in X as follows:

$$y_{(2n+1)} = Sx_{2n} = Bx_{(2n+1)}, y_{(2n+2)} = Tx_{(2n+1)} = Ax_{(2n+2)}, \quad (2.3)$$

for all $n = 0, 1, 2, \dots$. Define $d_n = d(y_n, y_{(n+1)})$. Suppose that $d_{2n} = 0$ for some n . Then $y_{2n} = y_{(2n+1)}$, that is, $Tx_{(2n-1)} = Ax_{2n} = Sx_{2n} = Bx_{(2n+1)}$, and A and S have a coincidence point. Similarly, if $d_{(2n+1)} = 0$, then B and T have a coincidence point. Assume that $d_n \neq 0$ for each n .

from (2.2), we have

$$\psi(d(Sx_{2n}, Tx_{(2n+1)})) \leq \psi(m(x_{2n}, x_{(2n+1)})) - \phi(m(x_{2n}, x_{(2n+1)})), \tag{2.4}$$

where

$$\begin{aligned} m(x_{2n}, x_{(2n+1)}) &= \max\{d(Ax_{2n}, Bx_{(2n+1)}), d(Sx_{2n}, Ax_{2n}), \\ &\quad \frac{d(Sx_{2n}, Bx_{(2n+1)}) + d(Tx_{(2n+1)}, Ax_{2n})}{2} \\ &\quad d(Tx_{(2n+1)}, Bx_{(2n+1)})\} \\ &= \max\{d_{2n}, d_{(2n+1)}\} \end{aligned} \tag{2.5}$$

Thus, from (2.4), we have

$$\psi(d(Sx_{2n}, Tx_{(2n+1)})) \leq \psi(\max\{d_{2n}, d_{(2n+1)}\}) - \phi(\max\{d_{2n}, d_{(2n+1)}\}). \tag{2.6}$$

Now, if $d_{(2n+1)} \geq d_{2n}$, for some n , then from (2.6), we have

$$\begin{aligned} \psi(d_{(2n+1)}) &\leq \psi(d_{(2n+1)}) - \phi(d_{(2n+1)}) \\ &< \psi(d_{(2n+1)}), \end{aligned} \tag{2.7}$$

which is a contradiction. Thus, $d_{2n} > d_{(2n+1)}$ for all n , and so, from (2.6), we have

$$\psi(d_{(2n+1)}) \leq \psi(d_{2n}) - \phi(d_{2n}), \text{ for all } n \in \mathbb{N}. \tag{2.8}$$

Similarly,

$$\begin{aligned} \psi(d_{2n}) &\leq \psi(d_{(2n-1)}) - \psi(d_{(2n-1)}), \\ \psi(d_{(2n-1)}) &\leq \psi(d_{(2n-2)}) - \phi(d_{(2n-2)}). \end{aligned}$$

In general, we have for all $n = 1, 2, \dots$,

$$\begin{aligned} \psi(d_n) &\leq \psi(d_{(n-1)}) - \phi(d_{(n-1)}) \\ &< \psi(d_{(n-1)}). \end{aligned} \tag{2.9}$$

Hence the sequence $\{\psi(d_n)\}$ is monotonically decreasing and bounded below. Thus, there exists, $r \geq 0$, such that

$$\lim_{n \rightarrow \infty} \psi(d_n) = r. \tag{2.10}$$

From(9), we deduce that

$$0 \leq \phi(d_{(n-1)}) \leq \psi(d_{(n-1)}) - \psi(d_n).$$

Letting limit as $n \rightarrow \infty$ and using (10), we get $\lim_{n \rightarrow \infty} \phi(d_{(n-1)}) = 0$ implies that

$$\lim_{n \rightarrow \infty} \phi(d_{(n-1)}) = \lim_{n \rightarrow \infty} (d(y_{(n-1)}, y_n)) = 0, \tag{2.11}$$

or

$$\lim_{n \rightarrow \infty} d_n = \lim_{n \rightarrow \infty} d(y_n, y_{(n+1)}) = 0. \quad (2.12)$$

Now, we show that $\{y_n\}$ is a Cauchy sequence. For this, it is sufficient to show that $\{y_{2n}\}$ is a Cauchy sequence. Let, if possible, $\{y_{2n}\}$ is not a Cauchy sequence. Then there exists an $\varepsilon > 0$ such that for each even integer $2k$ there exists even integers $2m(k) > 2n(k) > 2k$ such that

$$d(y_{(2n(k))}, y_{(2m(k))}) \geq \varepsilon. \quad (2.13)$$

For every even integer $2k$, suppose that $2m(k)$ be the least positive integer exceeding $2n(k)$ satisfying (13) such that

$$d(y_{2n(k)}, y_{(2m(k)-2)}) < \varepsilon. \quad (2.14)$$

from (2.13), we have

$$\begin{aligned} \varepsilon &\leq d(y_{2n(k)}, y_{2m(k)}) \\ &\leq d(y_{2n(k)}, y_{(2m(k)-2)}) + d(y_{(2m(k)-2)}, y_{(2m(k)-1)}) + d(y_{(2m(k)-1)}, y_{2m(k)}). \end{aligned}$$

Using (12) and (14) in the above inequality, we get

$$\lim_{k \rightarrow \infty} d(y_{2n(k)}, y_{2m(k)}) = \varepsilon. \quad (2.15)$$

Also, by the triangular inequality,

$$|d(y_{(2n(k))}, y_{(2m(k)-1)}) + d(y_{(2n(k))} y_{(2m(k))})| \leq d_{(2m(k)-1)},$$

$$|d(y_{(2n(k)+1)}, y_{(2m(k)-1)}) + d(y_{(2n(k))}, y_{(2m(k))})| \leq d_{(2m(k)-1)} + d_{2m(k)}. \quad (2.16)$$

Using (12), we get

$$\lim_{k \rightarrow \infty} d(y_{2n(k)}, y_{(2m(k)-1)}) = \lim_{k \rightarrow \infty} d(y_{(2n(k)+1)}, y_{(2m(k)-1)}) = \varepsilon. \quad (2.17)$$

from (2.2), we have

$$\begin{aligned} \psi(d(Sx_{2n(k)}, Tx_{(2m(k)-1)})) &\leq \psi(m(x_{(2n(k))}, x_{(2m(k)-1)})) \\ &\quad - \phi(m(x_{(2n(k))}, x_{(2m(k)-1)})), \end{aligned} \quad (2.18)$$

where

$$\begin{aligned} m(x_{2n(k)}, x_{(2m(k)-1)}) &= \max\{d(Ax_{2n(k)}, Bx_{(2m(k)-1)}), d(Sx_{2n(k)}, Ax_{2n(k)}), \\ &\quad \frac{(d(Sx_{2n(k)}, Bx_{(2m(k)-1)}) + d(Tx_{2n(k)}, Ax_{(2m(k)-1)}))}{2}, \\ &\quad d(Tx_{(2m(k)-1)}, Bx_{(2m(k)-1)})\} \\ &= \max\{d(y_{2n(k)}, y_{(2m(k)-1)}), d(y_{2n(k)}, y_{(2n(k)+1)}), \\ &\quad \frac{(d(y_{(2n(k)+1)}, y_{(2m(k)-1)}) + d(y_{2n(k)}, y_{(2m(k)-1)}))}{2}, \\ &\quad d(y_{(2m(k)-1)}, y_{2m(k)})\}. \end{aligned}$$

Letting limit as $k \rightarrow \infty$ and using (17), we get

$$\psi(\varepsilon) \leq \psi(\varepsilon) - \phi(\varepsilon),$$

which is a contradiction, since $\varepsilon > 0$. Thus, $\{y_{2n}\}$ is a Cauchy sequence and so $\{y_n\}$ is a Cauchy sequence. Now, suppose that $A(X)$ is complete. Note that $\{y_{2n}\}$ is contained in $A(X)$ and has a limit in $A(X)$, say u , that is, $\lim_{n \rightarrow \infty} y_{2n} = u$. Let $v \in A^{(-1)}u$. Then $Av = u$. Now, we shall prove that $Sv = u$. Let, if possible, $Sv \neq u$, that is, $d(Sv, u) = p > 0$.

Putting $x = v$ and $y = x_{(2n-1)}$ in (1.2), we have

$$\psi(d(Sv, Tx_{(2n-1)})) \leq \psi(m(v, x_{(2n-1)}) - \phi(m(v, x_{(2n-1)})).$$

Letting limit as $n \rightarrow \infty$, we have

$$\begin{aligned} \lim_{n \rightarrow \infty} \psi(d(Sv, Tx_{(2n-1)})) &\leq \lim_{n \rightarrow \infty} \psi(m(v, x_{(2n-1)}) \\ &\quad - \lim_{n \rightarrow \infty} \phi(m(v, x_{(2n-1)})), \end{aligned} \tag{2.19}$$

where,

$$\begin{aligned} \lim_{n \rightarrow \infty} m(v, x_{(2n-1)}) &= \lim_{n \rightarrow \infty} [\max\{d(u, y_{(2n-1)}), d(Sv, u), d(y_{2n}, y_{(2n-1)}), \\ &\quad \frac{(d(Sv, y_{(2n-1)}) + d(y_{2n}, u))}{2}\}] \\ &= \max\{d(u, u), d(Sv, u), d(u, u), \frac{1}{2}(d(Sv, u) + d(u, u))\} \\ &= d(Sv, u) = p. \end{aligned}$$

Thus, from (2.19), we have

$$\psi(d(Sv, u)) \leq \psi(p) - \phi(p),$$

that is

$$\psi(p) \leq \psi(p) - \phi(p),$$

which is a contradiction, since $p > 0$. Thus, $Sv = u = Av$. Hence u is the coincidence point of the pair (A, S) . Since $SX \subseteq BX$, $Sv = u$, implies that, $u \in BX$. Let $w \in B^{(-1)}u$. Then $Bw = u$. By using the same arguments as above, one can easily verify that, $Tw = u = Bw$, that is, u is the coincidence point of the pair (B, T) . The same result holds, if we assume that BX is complete instead of AX . Now, if TX is complete, then by (1), $u \in TX \subseteq AX$. Similarly, if SX is complete, then $u \in SX \subseteq BX$. Now, since the pairs (A, S) and (B, T) are weakly compatible, so

$$u = Sv = Av = Tw = Bw,$$

then

$$\begin{aligned} Au &= ASv = SAV = Su, \\ Bu &= BTw = TBw = Tu. \end{aligned} \tag{2.20}$$

Now, we claim that $Tu = u$. Let, if possible, $Tu \neq u$.
from (2.2), we have

$$\begin{aligned}\psi(d(u, Tu)) &= \psi(d(Sv, Tu)) \\ &\leq \psi(m(v, u)) - \phi(m(v, u)),\end{aligned}$$

where

$$\begin{aligned}m(v, u) &= \max\{d(Av, Bu), d(Sv, Av), d(Tu, Bu), \frac{1}{2}(d(Sv, Bu) + d(Tu, Av))\} \\ &= \max\{d(u, Tu), d(u, u), 0, \frac{1}{2}(d(u, Tu) + d(Tu, u))\} \\ &= d(u, Tu).\end{aligned}$$

Thus, we have

$$\begin{aligned}\psi(d(u, Tu)) &\leq \psi(d(u, Tu)) - \phi(d(u, Tu)) \\ &< \psi(d(u, Tu)),\end{aligned}$$

which is a contradiction. So, $Tu = u$. Similarly, $Su = u$. Thus, we get $Au = Su = Bu = Tu = u$. Hence u is the common fixed point of A, B, S and T . For the uniqueness, let z be another common fixed point of A, B, S and T .

Now, we claim that $u = z$. Let, if possible, $u \neq z$.
from (2.2), we have

$$\begin{aligned}\psi(d(u, z)) &= \psi(d(Su, Tz)) \\ &\leq \psi(m(u, z)) - \phi(m(u, z)) \\ &= \psi(d(u, z)) - \phi(d(u, z)),\end{aligned}$$

since

$$\begin{aligned}m(u, z) &= d(u, z) \\ &< \psi(d(u, z)),\end{aligned}$$

a contradiction. Thus, $u = z$, and the uniqueness follows.

Theorem 2.2. Let A, B, S and T be self mappings of a metric space (X, d) satisfying (1), (2) and the followings:

$$\text{pairs } (A, S) \text{ and } (B, T) \text{ are weakly compatible,} \quad (2.21)$$

$$\text{pair } (A, S) \text{ or } (B, T) \text{ satisfy the E.A. property.} \quad (2.22)$$

If any one of AX, BX, SX and TX is a complete subspace of X , then A, B, S and T have a unique common fixed point.

Proof: Suppose that (A, S) satisfies the *E.A.* property. Then there exists a sequence $\{x_n\}$ in X such that $\lim_{n \rightarrow \infty} Ax_n = \lim_{n \rightarrow \infty} Sx_n = z$, for some z in

X . Since $SX \subseteq BX$, there exists a sequence $\{y_n\}$ in X such that $Sx_n = By_n$. Hence $\lim_{n \rightarrow \infty} By_n = z$. We shall show that $\lim_{n \rightarrow \infty} Ty_n = z$. Let, if possible, $\lim_{n \rightarrow \infty} Ty_n = t = z$.

from (2.2), we have

$$\psi(d(Sx_n, Ty_n)) \leq \psi(m(x_n, y_n)) - \phi(m(x_n, y_n)).$$

Letting limit as $n \rightarrow \infty$, we have

$$\lim_{n \rightarrow \infty} \psi(d(Sx_n, Ty_n)) \leq \lim_{n \rightarrow \infty} \psi(m(x_n, y_n)) - \lim_{n \rightarrow \infty} \phi(m(x_n, y_n)), \tag{2.23}$$

where,

$$\begin{aligned} \lim_{n \rightarrow \infty} m(x_n, y_n) &= \lim_{n \rightarrow \infty} [\max\{d(Ax_n, By_n), d(Sx_n, Ax_n), d(Ty_n, By_n), \\ &\quad \frac{1}{2}(d(Sx_n, By_n) + d(Ty_n, Ax_n))\}] \\ &= \max\{d(z, z), d(z, z), d(t, z), \frac{1}{2}(d(z, z) + d(t, z))\} \\ &= d(t, z). \end{aligned}$$

Thus, from (2.23), we get

$$\begin{aligned} \psi(d(z, t)) &\leq \psi(d(z, t)) - \phi(d(z, t)) \\ &< \psi(d(z, t)), \end{aligned}$$

which is a contradiction. Therefore, $t = z$, that is, $\lim_{n \rightarrow \infty} Ty_n = z$. Suppose that BX is a complete subspace of X . Then $z = Bu$ for some u in X . Subsequently, we have

$$\lim_{n \rightarrow \infty} Ty_n = \lim_{n \rightarrow \infty} Sx_n = \lim_{n \rightarrow \infty} Ax_n = \lim_{n \rightarrow \infty} By_n = z = Bu.$$

Now, we shall show that $Tu = Bu$. Let, if possible, $Tu \neq Bu$.

from (2.2), we have

$$\psi(d(Sx_n, Tu)) \leq \psi(m(x_n, u)) - \phi(m(x_n, u)).$$

Letting limit as $n \rightarrow \infty$, we have

$$\lim_{n \rightarrow \infty} \psi(d(Sx_n, Tu)) \leq \lim_{n \rightarrow \infty} \psi(m(x_n, u)) - \lim_{n \rightarrow \infty} \phi(m(x_n, u)), \tag{2.24}$$

where

$$\begin{aligned} \lim_{n \rightarrow \infty} m(x_n, u) &= \lim_{n \rightarrow \infty} [\max\{d(Ax_n, Bu), d(Sx_n, Ax_n), d(Tu, Bu), \\ &\quad \frac{1}{2}(d(Sx_n, Bu) + d(Tu, Ax_n))\}] \\ &= \max\{d(z, z), d(z, z), d(Tu, z), \frac{1}{2}(d(z, z) + d(Tu, z))\} \\ &= d(Tu, z). \end{aligned}$$

Thus, from (2.24), we have

$$\begin{aligned}\psi(d(z, Tu)) &\leq \psi(d(z, Tu)) - \phi(d(z, Tu)) \\ &< \psi(d(z, Tu)),\end{aligned}$$

which is a contradiction. Therefore, $Tu = z = Bu$. Since B and T are weakly compatible, therefore, $BTu = TBu$, implies that, $TTu = TBu = BTu = BBu$. Since $TX \subseteq AX$, there exists $v \in X$, such that, $Tu = Av$.

Now, we claim that $Av = Sv$. Let, if possible, $Av \neq Sv$.

from (2.2), we have

$$\psi(d(Sv, Tu)) \leq \psi(m(v, u)) - \phi(m(v, u)), \quad (2.25)$$

where

$$\begin{aligned}m(v, u) &= \max\{d(Av, Bu), d(Sv, Av), d(Tu, Bu), \frac{1}{2}(d(Sv, Bu) + d(Tu, Av))\} \\ &= d(Sv, Av) = d(Sv, Tu).\end{aligned}$$

Thus, from (2.25), we have

$$\begin{aligned}\psi(d(Sv, Tu)) &\leq \psi(d(Sv, Tu)) - \phi(d(Sv, Tu)) \\ &< \psi(d(Sv, Tu)),\end{aligned}$$

which is a contradiction. Therefore, $Sv = Tu = Av$. Thus, we have, $Tu = Bu = Sv = Av$. The weak compatibility of A and S implies that $ASv = SAV = SSv = AAv$. Now, we claim that Tu is the common fixed point of A , B , S and T . Suppose that, $TTu \neq Tu$.

from (2.2), we have

$$\begin{aligned}\psi(d(Tu, TTu)) &= \psi(d(Sv, TTu)) \\ &\leq \psi(m(v, Tu)) - \psi(m(v, Tu)),\end{aligned} \quad (2.26)$$

where

$$\begin{aligned}m(v, Tu) &= \max\{d(Av, BTu), d(Sv, Av), d(BTu, TTu), \\ &\quad \frac{1}{2}(d(Sv, BTu) + d(TTu, Av))\} \\ &= \max\{d(Tu, TTu), 0, 0, d(Tu, TTu)\} \\ &= d(Tu, TTu).\end{aligned}$$

Thus, from (2.26), we have

$$\begin{aligned}\psi(d(Tu, TTu)) &\leq \psi(d(Tu, TTu)) - \phi(d(Tu, TTu)) \\ &< \psi(d(Tu, TTu)),\end{aligned}$$

which is a contradiction. Therefore, $Tu = TTu = BTu$. Hence Tu is the common fixed point of B and T . Similarly, we prove that Sv is the common fixed point of

A and S . Since $Tu = Sv$, Tu is the common fixed point of A, B, S and T . The proof is similar when AX is assumed to be a complete subspace of X . The cases in which or SX is a complete subspace of X are similar to the cases in which AX or BX , respectively is complete subspace of X , since $TX \subseteq AX$ and $SX \subseteq BX$.

Now, we shall prove that the common fixed point is unique. If possible, let p and q be two common fixed points of A, B, S and T , such that, $p \neq q$.

from (2.2), we have

$$\begin{aligned} \psi(d(p, q)) &= \psi(d(Sp, Tq)) \\ &\leq \psi(m(p, q)) - \phi(m(p, q)), \end{aligned} \tag{2.27}$$

where

$$\begin{aligned} m(p, q) &= \max\{d(Ap, Bq), d(Sp, Aq), d(Bq, Tq), \frac{1}{2}(d(Sp, Bq) + d(Tq, Ap))\} \\ &= \max\{d(p, q), 0, 0, d(p, q)\} \\ &= d(p, q). \end{aligned}$$

Thus, from (2.27), we have

$$\begin{aligned} \psi(d(p, q)) &\leq \psi(d(p, q)) - \phi(d(p, q)) \\ &< \psi(d(p, q)), \end{aligned}$$

which is a contradiction. Therefore, $p = q$, and the uniqueness follows.

Theorem 2.3. Let A, B, S and T be self maps of a metric space (X, d) satisfying (2), (21) and the following:

$$\begin{aligned} SX \subseteq BX \text{ and the pair } (A, S) \text{ satisfies } (CLR_A) \text{ property or} & \tag{2.28} \\ TX \subseteq AX \text{ and the pair } (B, T) \text{ satisfies } (CLR_B) \text{ property.} & \end{aligned}$$

Then A, B, S and T have a unique common fixed point.

Proof: Without loss of generality, assume that $SX \subseteq BX$ and the pair (A, S) satisfies (CLR_A) property, then there exists a sequence $\{x_n\}$ in X such that $\lim_{n \rightarrow \infty} Ax_n = \lim_{n \rightarrow \infty} Sx_n = Ax$, for some x in X . Since $SX \subseteq BX$, there exists a sequence $\{y_n\}$ in X such that $Sx_n = By_n$. Hence $\lim_{n \rightarrow \infty} By_n = Ax$. We shall show that $\lim_{n \rightarrow \infty} Ty_n = Ax$. Let, if possible, $\lim_{n \rightarrow \infty} Ty_n = z \neq Ax$.

from (2.2), we have

$$\psi(d(Sx_n, Ty_n)) \leq \psi(m(x_n, y_n)) - \phi(m(x_n, y_n)).$$

Letting limit as $n \rightarrow \infty$, we have

$$\lim_{n \rightarrow \infty} \psi(d(Sx_n, Ty_n)) \leq \lim_{n \rightarrow \infty} \psi(m(x_n, y_n)) - \lim_{n \rightarrow \infty} \phi(m(x_n, y_n)), \tag{2.29}$$

where

$$\begin{aligned}\lim_{n \rightarrow \infty} m(x_n, y_n) &= \lim_{n \rightarrow \infty} [\max\{d(Ax_n, By_n), d(Sx_n, Ax_n), d(Ty_n, By_n), \\ &\quad \frac{1}{2}(d(Sx_n, By_n) + d(Ty_n, Ax_n))\}] \\ &= \max\{d(Ax, Ax), d(Ax, Ax), d(z, Ax), \frac{1}{2}(d(z, z) + d(z, Ax))\} \\ &= d(z, Ax).\end{aligned}$$

Thus, from (2.29), we get

$$\begin{aligned}\psi(d(Ax, z)) &\leq \psi(d(Ax, z)) - \phi(d(Ax, z)) \\ &< \psi(d(Ax, z)),\end{aligned}$$

which is a contradiction. Therefore, $Ax = z$, that is, $\lim_{n \rightarrow \infty} Ty_n = Ax$. Subsequently, we have

$$\lim_{n \rightarrow \infty} Ax_n = \lim_{n \rightarrow \infty} Sx_n = \lim_{n \rightarrow \infty} By_n = \lim_{n \rightarrow \infty} Ty_n = Ax = z.$$

Now, we shall show that $Sx = z$. Let, if possible, $Sx \neq z$. from (2.2), we have

$$\psi(d(Sx, Ty_n)) \neq \psi(m(x, y_n)) - \phi(m(x, y_n)).$$

Letting limit as $n \rightarrow \infty$, we have

$$\lim_{n \rightarrow \infty} \psi(d(Sx, Ty_n)) \leq \lim_{n \rightarrow \infty} \psi(m(x, y_n)) - \lim_{n \rightarrow \infty} \phi(m(x, y_n)), \quad (2.30)$$

where

$$\begin{aligned}\lim_{n \rightarrow \infty} m(x, y_n) &= \lim_{n \rightarrow \infty} [\max\{d(Ax, By_n), d(Sx, Ax), d(Ty_n, By_n), \\ &\quad \frac{1}{2}(d(Sx, By_n) + d(Ty_n, Ax))\}] \\ &= \max\{d(z, z), d(Sx, z), d(z, z), \frac{1}{2}(d(Sx, z) + d(z, z))\} \\ &= d(Sx, z).\end{aligned}$$

Thus, from (2.30), we get

$$\begin{aligned}\psi(d(Sx, z)) &\leq \psi(d(Sx, z)) - \phi(d(Sx, z)) \\ &< \psi(d(Sx, z)),\end{aligned}$$

which is a contradiction. Therefore, $Sx = z = Ax$. Since, the pair (A, S) is weakly compatible, it follows that $Az = Sz$. Also, since $SX \subseteq BX$, there exists some y in X such that $Sx = By$, that is, $By = z$. Now, we show that $Ty = z$. Let, if possible, $Ty \neq z$.

from (2.2), we have

$$\psi(d(Sx_n, Ty) \leq \psi(m(x_n, y)) - \phi(m(x_n, y)).$$

Letting limit as $n \rightarrow \infty$, we have

$$\lim_{n \rightarrow \infty} \psi(d(Sx_n, Ty) \leq \lim_{n \rightarrow \infty} \psi(m(x_n, y)) - \lim_{n \rightarrow \infty} \phi(m(x_n, y)), \tag{2.31}$$

where

$$\begin{aligned} \lim_{n \rightarrow \infty} m(x_n, y) &= \lim_{n \rightarrow \infty} [\max\{d(Ax_n, By), d(Sx_n, Ax_n), d(Ty, By), \\ &\quad \frac{1}{2}(d(Sx_n, By) + d(Ty, Ax_n))\}] \\ &= \max\{d(z, z), d(z, z), d(z, Ty), \frac{1}{2}(d(z, z) + d(Ty, z))\} \\ &= d(z, Ty). \end{aligned}$$

Thus, from (2.31), we get

$$\begin{aligned} \psi(d(z, Ty) &\leq \psi(d(z, Ty)) - \phi(d(z, Ty)) \\ &< \psi(d(z, Ty)), \end{aligned}$$

which is a contradiction. Thus, $z = Ty = By$. Since the pair (B, T) is weakly compatible, it follows that $Tz = Bz$. Now, we claim that $Sz = Tz$. Let, if possible, $Sz \neq Tz$.

from (2.2), we have

$$\psi(d(Sz, Tz) \leq \psi(m(z, z)) - \phi(m(z, z)), \tag{2.32}$$

where

$$\begin{aligned} m(z, z) &= \max\{d(Az, Bz), d(Sz, Az), d(Bz, Tz), \frac{1}{2}(d(Sz, Bz) + d(Tz, Az)) \\ &= d(Sz, Tz). \end{aligned}$$

Thus, from (2.32), we have

$$\begin{aligned} \psi(d(Sz, Tz) &\leq \psi(d(Sz, Tz)) - \phi(d(Sz, Tz)) \\ &< \psi(d(Sz, Tz)), \end{aligned}$$

which is a contradiction. Therefore, $Sz = Tz$, that is, $Az = Sz = Tz = Bz$. Now, we shall show that $z = Tz$. Let, if possible, $z \neq Tz$.

from (2.2), we have

$$\psi(d(Sx, Tz) \leq \psi(m(x, z)) - \phi(m(x, z)), \tag{2.33}$$

where

$$\begin{aligned} m(x, z) &= \max\{d(Ax, Bz), d(Sx, Ax), d(Bz, Tz), \frac{1}{2}(d(Sx, Bz) + d(Tz, Ax))\} \\ &= d(Sx, Tz) = d(z, Tz). \end{aligned}$$

Thus, from (2.33), we have

$$\begin{aligned} \psi(d(z, Tz)) &\leq \psi(d(z, Tz)) - \phi(d(z, Tz)) \\ &< \psi(d(z, Tz)), \end{aligned}$$

which is a contradiction. Therefore, $z = Tz = Bz = Az = Sz$. Hence z is the common fixed point of A, B, S and T . Now, we shall prove that the common fixed point is unique. Let u be another common fixed point of A, B, S and T . Let, if possible, $z \neq u$.

from (2.2), we have

$$\begin{aligned} \psi(d(u, z)) &= \psi(d(Su, Tz)) \\ &\leq \psi(m(u, z)) - \phi(m(u, z)) \\ &= \psi(d(u, z)) - \phi(d(u, z)), \text{ since } m(u, z) = d(u, z) \\ &< \psi(d(u, z)), \end{aligned}$$

which is a contradiction. Thus, $u = z$, and hence the uniqueness follows.

Example 2.4. Let $X = [0, 1]$ be endowed with the Euclidean metric $d(x, y) = |x - y|$. Let the self maps A, B, S and T be defined by

$$Sx = \frac{x}{8}, Bx = \frac{x}{4}, Tx = \frac{x}{2}, Ax = x.$$

Clearly,

$$SX = [0, \frac{1}{8}] \subseteq [0, \frac{1}{4}] = BX,$$

$$TX = [0, \frac{1}{2}] \subseteq [0, 1] = AX.$$

Also AX is complete subspace of X and pairs $(A, S), (B, T)$ are weakly compatible. Now,

$$\begin{aligned} d(Sx, Ty) &= |\frac{x}{8} - \frac{y}{2}| = \frac{x}{8}|x - 4y|. \\ d(Ax, By) &= |x - \frac{y}{4}| = \frac{1}{4}|4x - y|. \\ d(Sx, Ax) &= |\frac{x}{8} - x| = \frac{7}{8}x. \\ d(By, Ty) &= |\frac{y}{4} - \frac{y}{2}| = \frac{y}{4}. \\ \frac{d(Sx, By) + d(Ty, Ax)}{2} &= \frac{1}{2}[|\frac{x}{8} - \frac{y}{4}| + |\frac{y}{2} - x|] \\ &= \frac{1}{16}[|x - 2y| + 4|y - 2x|]. \end{aligned}$$

Let $\psi(t) = \frac{t}{3}$ and $\phi(t) = \frac{t}{6}$. Thus, we have

$$\psi(d(Sx, Ty)) = \frac{1}{24}|x - 4y|.$$

$$\begin{aligned} m(x, y) &= \max\{d(Ax, By), d(Sx, Ax), d(Ty, By), \frac{1}{2}(d(Sx, By) + d(Ty, Ax))\} \\ &= d(Sx, Ax). \end{aligned}$$

Therefore,

$$\begin{aligned} \psi(d(Sx, Ax)) &= \frac{1}{3}\left(\frac{7}{8}x\right) = \frac{7}{24}x. \\ \phi(d(Sx, Ax)) &= \frac{1}{6}\left(\frac{7}{8}x\right) = \frac{7}{48}x. \end{aligned}$$

Thus, we have

$$\psi(m(x, y)) - \phi(m(x, y)) = \frac{7}{24}x - \frac{7}{48}x = \frac{7}{48}x.$$

Therefore,

$$\psi(d(Sx, Ty)) \leq \psi(m(x, y)) - \phi(m(x, y)).$$

Hence condition (2) is satisfied. If, we consider the sequence $\{x_n\} = \{\frac{1}{n}\}$, then

$$\begin{aligned} \lim_{n \rightarrow \infty} Ax_n &= \lim_{n \rightarrow \infty} x_n = \lim_{n \rightarrow \infty} \frac{1}{n} = 0. \\ \lim_{n \rightarrow \infty} Sx_n &= \lim_{n \rightarrow \infty} x_{\frac{n}{8}} = \lim_{n \rightarrow \infty} \frac{1}{8n} = 0. \end{aligned}$$

Therefore,

$$\lim_{n \rightarrow \infty} Ax_n = \lim_{n \rightarrow \infty} Sx_n = 0, \text{ where } 0 \in X.$$

So the pair (A, S) satisfies the *E.A.* property. Also,

$$\lim_{n \rightarrow \infty} Ax_n = \lim_{n \rightarrow \infty} Ax_n = 0 = A(0).$$

So the pair (A, S) satisfies the (CLR_A) property. Hence all the conditions of above Theorems are satisfied. Here 0 is the unique common fixed point of A, S, B and T .

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