



## On Derivations of Prime and Semi-prime Gamma Rings

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**ABSTRACT:** The concept of  $\Gamma$ -ring is a generalization of ring. Two important classes of  $\Gamma$ -rings are prime and semi-prime  $\Gamma$ -rings. In this paper, we consider the concept of derivations on prime and semi-prime  $\Gamma$ -rings and we study some of their properties.

**Key Words:**  $\Gamma$ -ring, derivation, bi- $(\sigma, \tau)$  derivation, trace.

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### 1. Introduction

In [11], Nobusawa introduced  $\Gamma$ -rings as a generalization of ternary rings. Barnes [2] weakened slightly the conditions in the definition of  $\Gamma$ -ring in the sense of Nobusawa. Barnes [2], Luh [9] and Kyuno [8] studied the structure of  $\Gamma$ -rings and obtained various generalizations analogous to corresponding parts in ring theory. Since then, some papers have been published on the topic of  $\Gamma$ -rings [1,5,7,10,12]. In [6], Chakraborty and Pau defined an isomorphism, an anti-isomorphism and a Jordan isomorphism in a  $\Gamma$ -ring and developed some important results relating to these concepts, also see [13,14].

The  $\Gamma$ -rings are defined in [11] as follows. Let  $M$  and  $\Gamma$  be additive abelian groups. If for all  $a, b, c \in M$  and  $\alpha, \beta \in \Gamma$ , the following conditions are satisfied: (i)  $a\alpha b \in M$ ; (ii)  $(a + b)\alpha c = a\alpha c + b\alpha c$ ; (iii)  $a(\alpha + \beta)b = a\alpha b + a\beta b$ ,  $a\alpha(b + c) = a\alpha b + a\alpha c$ ; (iv)  $(a\alpha b)\beta c = a\alpha(b\beta c)$ ; then  $M$  is called a  $\Gamma$ -ring, (in the sense of [2]). Every ring is a  $\Gamma$ -ring. A *right* (*left*, respectively) *ideal* of a  $\Gamma$ -ring  $M$  is an additive subgroup  $U$  of  $M$  such that  $U\Gamma M \subseteq U$  ( $M\Gamma U \subseteq U$ , respectively). If  $U$  is both right and left ideal, then we say  $U$  is an *ideal* of  $M$ . If the following condition holds for a  $\Gamma$ -ring  $M$ , then  $M$  is called a *prime*  $\Gamma$ -ring:  $a\Gamma M\Gamma b = 0 \Rightarrow a = 0$  or  $b = 0$ , where  $a, b \in M$ . Also,  $M$  is called a *semi prime*  $\Gamma$ -ring, if  $a\Gamma M\Gamma a = 0$  implies that  $a = 0$ , where  $a \in M$ . We refer to [1,3,6,7,15,16] to see more results about prime and semiprime rings. Throughout this paper all  $\Gamma$ -rings will be associative. An additive mapping  $D : M \rightarrow M$  is called a *derivation* if  $D(x\gamma y) = D(x)\gamma y + x\gamma D(y)$  holds for all  $x, y \in M$  and  $\gamma \in \Gamma$ . A mapping  $B(.,.) : M \times M \rightarrow M$  is said to be *symmetric* if  $B(x, y) = B(y, x)$  holds for all pairs  $x, y \in M$ . A mapping  $f : M \rightarrow M$  defined by  $f(x) = B(x, x)$ , where  $B(.,.) : M \times M \rightarrow$

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$M$  is a symmetric mapping, is called the *trace* of  $B$ . It is obvious that, in case  $B(.,.) : M \times M \rightarrow M$  is a symmetric mapping which is also bi-additive, then trace of  $B$  satisfies the relation  $f(x+y) = f(x) + f(y) + 2B(x,y)$ , for all  $x, y \in M$ . We shall use also the fact that trace of symmetric bi-additive mapping is an even function. Let  $\sigma, \tau$  be endomorphisms of  $\Gamma$ -ring  $M$ . A symmetric bi-additive mapping  $D(.,.) : M \times M \rightarrow M$  is called a *symmetric bi- $(\sigma, \tau)$  derivation*, if  $D(x\gamma y, z) = D(x, z)\gamma\sigma(y) + \tau(x)\gamma D(y, z)$  is fulfilled for all  $x, y, z \in M$  and  $\gamma \in \Gamma$ . Obviously, in this case also the relation  $D(x, y\gamma z) = D(x, y)\gamma\sigma(z) + \tau(y)\gamma D(x, z)$  holds for all  $x, y, z \in M$  and  $\gamma \in \Gamma$ .

## 2. Main results

In the proofs of several theorems in [4], the authors used the following lemma:

(Lemma 1, [4]). Let  $D : M \rightarrow M$  be a derivation, where  $M$  is a prime  $\Gamma$ -ring. Let  $U$  be a nonzero right ideal of  $M$ . Suppose either

$$(i) \quad a\gamma D(x) = 0, \quad x \in U \text{ and } \gamma \in \Gamma,$$

$$(ii) \quad D(x)\gamma a = 0, \quad x \in U \text{ and } \gamma \in \Gamma,$$

holds. In both cases, we have  $a = 0$  or  $D = 0$ .

Unfortunately, the proofs of some theorems are not correct. In order to correct them, we use the following lemmas instead of Lemma 1 in [4].

**Lemma 2.1.** *Let  $M$  be a prime  $\Gamma$ -ring,  $U$  be a nonzero ideal on  $M$  and  $\sigma, \tau$  be automorphisms of  $M$ . Also, let  $D : M \times M \rightarrow M$  be a symmetric bi- $(\sigma, \tau)$ -derivation and  $d$  denotes the trace of  $D$ . Then, for all  $x, y \in M$ ,*

$$(i) \quad \text{If } U\Gamma x = 0 \text{ or } x\Gamma U = 0, \text{ then } x = 0;$$

$$(ii) \quad \text{If } x\Gamma U\Gamma y = 0, \text{ then } x = 0 \text{ or } y = 0;$$

$$(iii) \quad \text{If } D(u, v) = 0, \text{ for all } u, v \in U, \text{ then } D = 0;$$

$$(iv) \quad \text{If } M \text{ is 2-torsion free and } d(U) = 0, \text{ then } D = 0.$$

**Proof:** (i) Suppose that  $U\Gamma x = 0$ , then  $u\gamma M\Gamma x \subseteq U\Gamma x = \{0\}$ , for all  $u \in U$  and  $\gamma \in \Gamma$ . So  $x = 0$ , since  $M$  is prime and  $U \neq 0$ . In the case  $x\Gamma U = 0$ , the proof is similar.

(ii) Suppose that  $x\Gamma U\Gamma y = 0$ , then  $x\Gamma U\Gamma M\Gamma y \subseteq x\Gamma U\Gamma y = \{0\}$ . Hence  $x\Gamma U = 0$  or  $y = 0$ , since  $M$  is prime. So by (i),  $x = 0$  or  $y = 0$ .

(iii) Suppose that  $D(u, v) = 0$ , for all  $u, v \in U$ . Replace  $u$  by  $r\gamma u$ , where  $r \in M$  and  $\gamma \in \Gamma$ , we get  $0 = D(r\gamma u, v) = D(r, v)\gamma\sigma(u) + \tau(r)\gamma D(u, v) = D(r, v)\gamma\sigma(u)$ . So,  $D(r, v) = 0$ , by (i). Replace  $v$  by  $s\beta v$ , where  $s \in M$  and  $\beta \in \Gamma$ , we get  $0 = D(r, s\beta v) = D(r, s)\beta\sigma(v) + \tau(s)\beta D(r, v) = D(r, s)\beta\sigma(v)$ . So,  $D(r, s) = 0$ , by (i). This means that  $D = 0$ .

(iv) Suppose that  $d(U) = 0$ , then  $2D(u, v) = d(u+v) - d(u) - d(v) = 0$ , for all

$u, v \in U$ . Thus,  $D(u, v) = 0$ , for all  $u, v \in U$ , since  $M$  is 2-torsion free. Now, (iii) completes the proof.  $\square$

**Lemma 2.2.** *Let  $M$  be a prime  $\Gamma$ -ring and  $D : M \times M \longrightarrow M$  be a symmetric bi- $(\sigma, \tau)$  derivation, where  $\sigma, \tau$  are automorphisms of  $M$ . Also, let  $U$  be a nonzero ideal of  $M$  and  $a \in M$ . Suppose either*

$$(i) \quad a\gamma D(u, v) = 0, \quad u, v \in U \text{ and } \gamma \in \Gamma,$$

$$(ii) \quad D(u, v)\gamma a = 0, \quad u, v \in U \text{ and } \gamma \in \Gamma,$$

*holds. In both cases, we have  $a = 0$  or  $D = 0$ .*

**Proof:** (i) Writing  $u\gamma r$  instead of  $u$  in  $a\gamma D(u, v) = 0$ , where  $u, v \in U$  and  $r \in M$ . We get

$$\begin{aligned} 0 &= a\gamma D(u\gamma r, v) = a\gamma(D(u, v)\gamma\sigma(r) + \tau(u)\gamma D(r, v)) \\ &= a\gamma D(u, v)\gamma\sigma(r) + a\gamma\tau(u)\gamma D(r, v) = a\gamma\tau(u)\gamma D(r, v), \end{aligned}$$

for all  $u, v \in U, r \in M$ . So,  $a\Gamma\tau(U)\Gamma D(r, v) = 0$ . This implies that  $a = 0$  or  $D = 0$ , by Lemma 2.1.

(ii) Writing  $r\gamma u$  instead of  $u$  in  $D(u, v)\gamma a = 0$ , where  $u, v \in U$  and  $r \in M$ . We get

$$\begin{aligned} 0 &= D(r\gamma u, v)\gamma a = (D(r, v)\gamma\sigma(u) + \tau(r)\gamma D(u, v))\gamma a \\ &= D(r, v)\gamma\sigma(u)\gamma a + \tau(r)\gamma D(u, v)\gamma a = D(r, v)\gamma\sigma(u)\gamma a, \end{aligned}$$

for all  $u, v \in U, r \in M$ . So,  $D(r, v)\Gamma\sigma(U)\Gamma a = 0$ . This implies that  $a = 0$  or  $D = 0$ , by Lemma 2.1.  $\square$

**Lemma 2.3.** *Let  $M$  be a 2-torsion free prime  $\Gamma$ -ring and  $U$  be a nonzero ideal of  $M$ . Also, let  $a, b \in M$  be fixed elements. If  $a\gamma u\beta b + b\gamma u\beta a = 0$  is fulfilled for all  $u \in U$  and  $\alpha, \beta \in \Gamma$ , then either  $a = 0$  or  $b = 0$ .*

(Theorem 1, [4]). Let  $M$  be a prime  $\Gamma$ -ring of characteristic not two and  $U$  be nonzero ideal of  $M$ . Suppose there exist symmetric bi- $(\sigma, \tau)$  derivations  $D_1(.,.) : M \times M \longrightarrow M$  and  $D_2(.,.) : M \times M \longrightarrow M$  such that  $D_1(d_2(u), u) = 0$  holds for all  $u \in U$ , where  $d_2$  denotes the trace of  $D_2$ . In this case  $D_1 = 0$  or  $D_2 = 0$ .

Now, we give a corrected version of the above theorem as follows:

**Theorem 2.4.** *Let  $M$  be a 2-torsion free prime  $\Gamma$ -ring,  $U$  be a nonzero ideal of  $M$  and  $\sigma, \tau$  be automorphisms of  $M$  such that  $\sigma(U) \subseteq U$  and  $\sigma = \tau$ . Also, let there exist symmetric bi- $(\sigma, \tau)$  derivations  $D_1(.,.), D_2(.,.) : M \times M \longrightarrow M$  such that  $D_1(d_2(u), \sigma(u)) = 0$  holds for all  $u \in U$ , where  $d_2$  denotes the trace of  $D_2$ . In this case  $D_1 = 0$  or  $D_2 = 0$ .*

**Proof:** By linearity of the relation

$$D_1(d_2(u), \sigma(u)) = 0, \quad (2.1)$$

one obtains

$$D_1(d_2(u) + d_2(v) + 2D_2(u, v), \sigma(u) + \sigma(v)) = 0, \text{ for all } u, v \in U,$$

whence

$$D_1(d_2(u), \sigma(v)) + D_1(d_2(v), \sigma(u)) + 2D_1(D_2(u, v), \sigma(u)) + 2D_1(D_2(u, v), \sigma(v)) = 0$$

according to (2.1). Substituting in the equation above  $u$  by  $-u$ , we obtain by comparing this new equation with the equation above that

$$D_1(d_2(u), \sigma(v)) + 2D_1(D_2(u, v), \sigma(u)) = 0 \quad (2.2)$$

is fulfilled for all pairs  $u, v \in U$ . Let us replace in (2.2)  $v$  by  $u\alpha v$ , where  $\alpha \in \Gamma$ . Then,

$$\begin{aligned} 0 &= D_1(d_2(u), \sigma(u\alpha v)) + 2D_1(D_2(u, u\alpha v), \sigma(u)) \\ &= D_1(d_2(u), \sigma(u)\alpha\sigma(v)) + 2D_1(d_2(u)\alpha\sigma(v) + \sigma(u)\alpha D_2(u, v), \sigma(u)) \\ &= D_1(d_2(u), \sigma(u))\alpha\sigma^2(v) + \sigma^2(u)\alpha D_1(d_2(u), \sigma(v)) \\ &\quad + 2D_1(d_2(u), \sigma(u))\alpha\sigma^2(v) + 2\sigma(d_2(u))\alpha D_1(\sigma(v), \sigma(u)) \\ &\quad + 2d_1(\sigma(u))\alpha\sigma(D_2(u, v)) + 2\sigma^2(u)\alpha D_1(D_2(u, v), \sigma(u)) \\ &= 2\sigma(d_2(u))\alpha D_1(\sigma(v), \sigma(u)) + 2d_1(\sigma(u))\alpha\sigma(D_2(u, v)), \end{aligned}$$

where  $d_1$  denotes the trace of  $D_1$ . In the above calculation, we used (2.1) and (2.2). Thus, we have

$$\sigma(d_2(u))\alpha D_1(\sigma(u), \sigma(v)) + d_1(\sigma(u))\alpha\sigma(D_2(u, v)) = 0, \quad (2.3)$$

for all  $u, v \in U$  and  $\alpha \in \Gamma$ . Let us write in (2.3),  $v\beta u$  instead of  $v$ , where  $\beta \in \Gamma$ . We have

$$\begin{aligned} 0 &= \sigma(d_2(u))\alpha D_1(\sigma(u), \sigma(v\beta u)) + d_1(\sigma(u))\alpha\sigma(D_2(u, v\beta u)) \\ &= \sigma(d_2(u))\alpha D_1(\sigma(u), \sigma(v)\beta\sigma(u)) + d_1(\sigma(u))\alpha\sigma(D_2(u, v)\beta\sigma(u) + \sigma(v)\beta d_2(u)) \\ &= \sigma(d_2(u))\alpha D_1(\sigma(u), \sigma(v))\beta\sigma^2(u) + \sigma(d_2(u))\alpha\sigma^2(v)\beta d_1(\sigma(u)) \\ &\quad + d_1(\sigma(u))\alpha\sigma(D_2(u, v))\beta\sigma^2(u) + d_1(\sigma(u))\alpha\sigma^2(v)\beta\sigma(d_2(u)) \\ &= \sigma(d_2(u))\alpha\sigma^2(v)\beta d_1(\sigma(u)) + d_1(\sigma(u))\alpha\sigma^2(v)\beta\sigma(d_2(u)). \end{aligned}$$

Thus, we have

$$\sigma(d_2(u))\alpha\sigma^2(v)\beta d_1(\sigma(u)) + d_1(\sigma(u))\alpha\sigma^2(v)\beta\sigma(d_2(u)) = 0, \quad (2.4)$$

for all  $u, v \in U$  and  $\alpha, \beta \in \Gamma$ . So, by Lemma 2.3, we have

$$d_2(u) = 0 \text{ or } d_1(\sigma(u)) = 0, \text{ for all } u \in U, \quad (2.5)$$

since  $\sigma$  is an automorphism and  $\sigma(U) \subseteq U$ . We claim that  $d_1(U) = 0$  and  $d_2(U) = 0$ . Suppose that  $d_1(U) \neq 0$  or  $d_2(U) \neq 0$ . So, there exist elements  $u_2, u_3 \in U$  such that  $d_1(u_3) \neq 0$  and  $d_2(u_2) \neq 0$ . There exists element  $u_1 \in U$  such that  $\sigma(u_1) = u_3$ , since  $\sigma$  is onto. Therefore, we have  $d_1\sigma(u_1) \neq 0$  and  $d_2(u_2) \neq 0$ . So,  $d_2(u_1) = 0$  and  $d_1\sigma(u_2) = 0$ , by (2.5). Let us replace  $u$  by  $u_2$  in (2.3), we get  $0 = \sigma d_2(u_2)\alpha D_1(\sigma(u_2), \sigma(v)) + d_1\sigma(u_2)\alpha\sigma D_2(u_2, v) = \sigma d_2(u_2)\alpha D_1(\sigma(u_2), \sigma(v))$ , for all  $v \in U$ . Using Lemma 2.2, we obtain that  $D_1(\sigma(u_2), \sigma(v)) = 0$ , for all  $v \in U$ . In particular, we have  $D_1(\sigma(u_1), \sigma(u_2)) = 0$ . So,  $d_1(\sigma(u_1 + u_2)) = d_1\sigma(u_1) + d_1\sigma(u_2) + 2D_1(\sigma(u_1), \sigma(u_2)) = d_1\sigma(u_1) \neq 0$ . Now, replace  $u$  by  $u_1$  in (2.3), we get  $0 = \sigma d_2(u_1)\alpha D_1(\sigma(u_1), \sigma(v)) + d_1\sigma(u_1)\alpha\sigma D_2(u_1, v) = d_1\sigma(u_1)\alpha\sigma D_2(u_1, v)$ , for all  $v \in U$ . Using Lemma 2.2, we obtain that  $D_2(u_1, v) = 0$ , for all  $v \in U$ . In particular, we have  $D_2(u_1, u_2) = 0$ . So,  $d_2(u_1 + u_2) = d_2(u_1) + d_2(u_2) + 2D_2(u_1, u_2) = d_2(u_2) \neq 0$ . If we set  $v = u_1 + u_2$ , then  $d_2(v) \neq 0$  and  $d_1\sigma(v) \neq 0$  and this is a contradiction with (2.5). So,  $d_1(U) = 0$  or  $d_2(U) = 0$ . This implies that  $D_1 = 0$  or  $D_2 = 0$ , by Lemma 2.1.  $\square$

(Theorem 2, [4]). Let  $M$  be a 2-torsion free semi-prime  $\Gamma$ -ring and  $U$  be a nonzero ideal of  $M$ . Suppose there exists such a symmetric bi- $(\sigma, \tau)$  derivation  $D(.,.) : M \times M \rightarrow M$  that  $D(d(u), u) = 0$  holds for all  $u \in U$ , where  $d$  denotes the trace of  $D$ . In this case we have  $D = 0$ .

Now, we give a corrected version of the above theorem as follows:

**Theorem 2.5.** *Let  $M$  be a 2-torsion free semi-prime  $\Gamma$ -ring,  $U$  be a nonzero ideal of  $M$  and  $\sigma, \tau$  be automorphisms of  $M$  such that  $\sigma(U) \subseteq U$  and  $\sigma = \tau$ . Also, let there exists symmetric bi- $(\sigma, \tau)$  derivation  $D(.,.) : M \times M \rightarrow M$  such that  $d\sigma = \sigma d$  and  $D(d(u), \sigma(u)) = 0$  holds for all  $u \in U$ , where  $d$  denotes the trace of  $D$ . In this case we have  $D = 0$ .*

**Proof:** In this case (2.4) of Theorem 2.4 reduces to

$$0 = \sigma(d(u))\alpha\sigma^2(v)\beta d(\sigma(u)) + d(\sigma(u))\alpha\sigma^2(v)\beta\sigma(d(u)) = 2\sigma(d(u))\alpha\sigma^2(v)\beta\sigma(d(u)),$$

for all  $u, v \in U$  and  $\alpha, \beta \in \Gamma$ . This implies that  $d(U) = 0$ , since  $M$  is 2-torsion free and semi-prime. Therefore  $D = 0$ , by Lemma 2.1.  $\square$

(Theorem 3, [4]). Let  $M$  be prime  $\Gamma$ -ring of characteristic not two and three. Let  $\tau(U) \subset U$ ,  $U$  be nonzero ideal of  $M$  and  $\sigma\tau = \tau\sigma$  and  $\sigma = \tau$ . Let  $D_1(.,.) : M \times M \rightarrow M$  and  $D_2(.,.) : M \times M \rightarrow M$  be symmetric bi- $(\sigma, \tau)$  derivations. Suppose further that there exists a symmetric bi-additive mapping  $B(.,.) : M \times M \rightarrow M$  such that  $d_1(d_2(u)) = f(u)$  holds for all  $u \in U$ , where  $d_1$  and  $d_2$  are the traces of  $D_1$  and  $D_2$  respectively, and  $f$  is the trace of  $B$ . Then either  $D_1 = 0$  or  $D_2 = 0$ .

Now, we give a corrected version of the above theorem as follows:

**Theorem 2.6.** *Let  $M$  be a 6-torsion free prime  $\Gamma$ -ring,  $U$  be a nonzero ideal of  $M$  and  $\sigma, \tau$  be automorphisms of  $M$  such that  $\sigma(U) \subseteq U$  and  $\sigma = \tau$ . Also, let*

$D_1(\cdot, \cdot), D_2(\cdot, \cdot) : M \times M \longrightarrow M$  be symmetric bi- $(\sigma, \tau)$  derivations and there exists a symmetric bi-additive mapping  $B(\cdot, \cdot) : M \times M \longrightarrow M$  such that  $d_1(d_2(u)) = f(u)$  holds for all  $u \in U$ , where  $d_1$  and  $d_2$  are the traces of  $D_1$  and  $D_2$ , respectively, and  $f$  is the trace of  $B$ . Then either  $D_1 = 0$  or  $D_2 = 0$ .

**Proof:** The linearity of the relation

$$d_1(d_2(u)) = f(u), \text{ for all } u \in U, \quad (2.6)$$

gives us

$$d_1(d_2(u) + d_2(v) + 2D_2(u, v)) = f(u) + f(v) + 2B(u, v), \text{ for all } u, v \in U.$$

Then, we have

$$\begin{aligned} & d_1(d_2(u) + d_2(v)) + 2d_1(D_2(u, v)) + 4D_1(d_2(u) + d_2(v), D_2(u, v)) \\ &= d_1(d_2(u)) + d_1(d_2(v)) + 2D_1(d_2(u), d_2(v)) + 2d_1(D_2(u, v)) \\ &\quad + 4D_1(d_2(u), D_2(u, v)) + 4D_1(d_2(v), D_2(u, v)) \\ &= f(u) + f(v) + 2B(u, v). \end{aligned}$$

Using (2.6), we arrive at

$$\begin{aligned} & D_1(d_2(u), d_2(v)) + d_1(D_2(u, v)) + 2D_1(d_2(u), D_2(u, v)) + 2D_1(d_2(v), D_2(u, v)) \\ &= B(u, v). \end{aligned}$$

Substituting in the equation above  $u$  by  $-u$ , we obtain by comparing this new equation with the equation above that

$$2D_1(d_2(u), D_2(u, v)) + 2D_1(d_2(v), D_2(u, v)) = B(u, v), \quad (2.7)$$

holds for all  $u, v \in U$ . Let us replace in (2.7)  $u$  by  $2u$ . We have

$$8D_1(d_2(u), D_2(u, v)) + 2D_1(d_2(v), D_2(u, v)) = B(u, v), \quad (2.8)$$

By comparing (2.7) and (2.8), we obtain  $6D_1(d_2(u), D_2(u, v)) = 0$ , which leads to

$$D_1(d_2(u), D_2(u, v)) = 0, \quad (2.9)$$

since, we have assumed that  $M$  is 6-torsion free. From (2.9) it follows that both terms on the left side of the relation (2.7) are zero, which means that  $B = 0$  on  $U$ . Hence (2.6) reduces to

$$d_1(d_2(u)) = 0, \text{ for all } u \in U. \quad (2.10)$$

Let in (2.9)  $v$  be  $v\alpha u$ , where  $\alpha \in \Gamma$ . We have

$$\begin{aligned} 0 &= D_1(d_2(u), D_2(u, v\alpha u)) = D_1(d_2(u), D_2(u, v)\alpha\sigma(u)) + D_1(d_2(u), \sigma(v)\alpha d_2(u)) \\ &= D_1(d_2(u), D_2(u, v))\alpha\sigma^2(u) + \sigma(D_2(u, v))\alpha D_1(d_2(u), \sigma(u)) \\ &\quad + D_1(d_2(u), \sigma(v))\alpha\sigma(d_2(u)) + \sigma^2(v)\alpha d_1(d_2(u)). \end{aligned}$$

Using (2.9) and (2.10), we arrive at

$$D_1(d_2(u), \sigma(v))\alpha\sigma(d_2(u)) + \sigma(D_2(u, v))\alpha D_1(d_2(u), \sigma(u)) = 0, \text{ for all } u, v \in U \tag{2.11}$$

Let us replace in (2.11),  $v$  by  $u\beta v$ , where  $\beta \in \Gamma$ . We have

$$\begin{aligned} 0 &= D_1(d_2(u), \sigma(u)\beta\sigma(v))\alpha\sigma(d_2(u)) + \sigma(D_2(u, u\beta v))\alpha D_1(d_2(u), \sigma(u)) \\ &= D_1(d_2(u), \sigma(u))\beta\sigma^2(v)\alpha\sigma(d_2(u)) + \sigma^2(u)\beta D_1(d_2(u), \sigma(v))\alpha\sigma(d_2(u)) \\ &\quad + \sigma(d_2(u))\beta\sigma^2(v)\alpha D_1(d_2(u), \sigma(u)) + \sigma^2(u)\beta\sigma(D_2(u, v))\alpha D_1(d_2(u), \sigma(u)) \end{aligned}$$

Now, by (2.11) we arrive finally at

$$D_1(d_2(u), \sigma(u))\beta\sigma^2(v)\alpha\sigma(d_2(u)) + \sigma(d_2(u))\beta\sigma^2(v)\alpha D_1(d_2(u), \sigma(u)) = 0, \tag{2.12}$$

for  $u, v \in U$  and  $\alpha, \beta \in \Gamma$ . So, we have  $d_2(u) = 0$  or  $D_1(d_2(u), \sigma(u)) = 0$ , by Lemma 2.3. If  $d_2(u) = 0$ , then  $D_1(d_2(u), \sigma(u)) = D_1(0, \sigma(u)) = 0$ . So, in general we have  $D_1(d_2(u), \sigma(u)) = 0$ , for all  $u \in U$ . Therefore,  $D_1 = 0$  or  $D_2 = 0$ , by Theorem 2.4.  $\square$

(Theorem 4, [4]). Let  $M$  be a semi-prime  $\Gamma$ -ring which is 2-torsion and 3-torsion free. Let  $d(U) \subset U$ ,  $\tau(U) \subset U$ ,  $\sigma(U) \subset U$ ,  $U$  be nonzero ideal of  $M$ ,  $\sigma\tau = \tau\sigma$  and  $\sigma = \tau$ . Let  $D(.,.) : M \times M \rightarrow M$  and  $B(.,.) : M \times M \rightarrow M$  be a symmetric bi- $(\sigma, \tau)$  derivation and a symmetric bi-additive mapping, respectively. Suppose that  $d(d(u)) = f(u)$  holds for all  $u \in U$ , where  $d$  is the trace of  $D$  and  $f$  is the trace of  $B$ . In this case we have  $D = 0$ .

Now, we give a corrected version of the above theorem as follows:

**Theorem 2.7.** *Let  $M$  be a 6-torsion free semi-prime  $\Gamma$ -ring,  $U$  be a nonzero ideal of  $M$  and  $\sigma, \tau$  be automorphisms of  $M$  such that  $\sigma(U) \subseteq U$  and  $\sigma = \tau$ . Also, let  $D(.,.) : M \times M \rightarrow M$  be a symmetric bi- $(\sigma, \tau)$  derivation such that  $\sigma D(.,.) = D(\sigma(.), \sigma(.))$  and  $B(.,.) : M \times M \rightarrow M$  be a symmetric bi-additive mapping. Suppose that  $d(d(u)) = f(u)$  holds for all  $u \in U$ , where  $d$  and  $f$  are the trace of  $D$  and  $B$ , respectively. In this case, we have  $D = 0$ .*

**Proof:** Obviously, we can use the beginning of the proof of Theorem 2.6. In this case, relations (2.9) and (2.10) can be written in the form

$$D(d(u), D(u, v)) = 0, \text{ for all } u, v \in U \tag{2.13}$$

and

$$d(d(u)) = 0, \text{ for all } u \in U. \tag{2.14}$$

Let us write in (2.13),  $v\alpha w$  instead of  $v$ , where  $w \in M$  and  $\alpha \in \Gamma$ . We have

$$\begin{aligned} 0 &= D(d(u), D(u, v\alpha w)) = D(d(u), D(u, v)\alpha\sigma(w)) + D(d(u), \sigma(v)\alpha D(u, w)) \\ &= D(d(u), D(u, v))\alpha\sigma^2(w) + \sigma(D(u, v))\alpha D(d(u), \sigma(w)) \\ &\quad + D(d(u), \sigma(v))\alpha\sigma(D(u, w)) + \sigma^2(v)\alpha D(d(u), D(u, w)). \end{aligned}$$

Hence by (2.13), we have

$$\sigma(D(u, v))\alpha D(d(u), \sigma(w)) + D(d(u), \sigma(v))\alpha\sigma(D(u, w)) = 0.$$

In particular, for  $w = \sigma^{-1}d(u)$  we obtain

$$\sigma(D(u, v))\alpha D(d(u), \sigma(\sigma^{-1}d(u))) + D(d(u), \sigma(v))\alpha\sigma(D(u, \sigma^{-1}d(u))) = 0.$$

So,

$$D(d(u), \sigma(v))\alpha\sigma(D(u, \sigma^{-1}d(u))) = 0, \text{ for all } u, v \in U. \quad (2.15)$$

according to (2.14). Replace in (2.15),  $v$  by  $u\beta v$ , where  $\beta \in \Gamma$ . We have

$$\begin{aligned} 0 &= D(d(u), \sigma(u\beta v))\alpha\sigma(D(u, \sigma^{-1}d(u))) \\ &= D(d(u), \sigma(u)\beta\sigma(v))\alpha\sigma(D(u, \sigma^{-1}d(u))) \\ &= D(d(u), \sigma(u))\beta\sigma^2(v)\alpha\sigma(D(u, \sigma^{-1}d(u))) \\ &\quad + \sigma^2(u)\beta D(d(u), \sigma(v))\alpha\sigma(D(u, \sigma^{-1}d(u))) \\ &= D(d(u), \sigma(u))\beta\sigma^2(v)\alpha\sigma(D(u, \sigma^{-1}d(u))) \\ &= D(d(u), \sigma(u))\beta\sigma^2(v)\alpha D(\sigma(u), d(u)) \\ &= D(d(u), \sigma(u))\beta\sigma^2(v)\alpha D(d(u), \sigma(u)), \end{aligned}$$

according to (2.15) and finally

$$D(d(u), \sigma(u)) = 0, \text{ for all } u \in U,$$

since we have assumed that  $M$  is semi-prime  $\Gamma$ -ring. Now, Theorem 2.5 completes the proof.  $\square$

**Remark 2.8.** In Example 1 in [4],  $d$  is not a symmetric bi- $(\sigma, \tau)$  derivation.

Let  $\sigma, \tau$  be endomorphisms of  $\Gamma$ -ring  $M$ . A symmetric bi-additive mapping  $D(.,.) : M \times M \rightarrow M$  is called a *symmetric bi- $(\sigma, \tau)$  derivation*, if

$$D(x\gamma y, z) = D(x, z)\gamma\sigma(y) + \tau(x)\gamma D(y, z)$$

is fulfilled for all  $x, y, z \in M$  and  $\gamma \in \Gamma$ .

**Example 2.1.** Let  $(R, +, \circ)$  be a commutative ring and  $\Gamma = \{\circ\}$ . Then  $M = (R, +, \Gamma)$  is  $\Gamma$ -ring. Also, let the functions  $\sigma, \tau : M \rightarrow M$  and  $D(.,.) : M \times M \rightarrow M$  be defined as  $\sigma(x) = x$ ,  $\tau(x) = 0$  and  $D(x, y) = x \circ y$ , for all  $x, y \in M$ . Then,  $\sigma, \tau$  are endomorphisms and  $D$  is symmetric bi- $(\sigma, \tau)$  derivation.

**Example 2.2.** Let  $(R, +, \circ)$  be a ring of characteristic 2 and  $\Gamma = \{\circ\}$ . Consider  $\Gamma$ -ring  $M = (R, +, \Gamma)$ . Define the functions  $\sigma, \tau : M \rightarrow M$  and  $D(.,.) : M \times M \rightarrow M$  as  $\sigma(x) = \tau(x) = x$  and  $D(x, y) = x \circ y + y \circ x$ , for all  $x, y \in M$ . Then,  $\sigma, \tau$  are endomorphisms and  $D$  is symmetric bi- $(\sigma, \tau)$  derivation.



**Example 2.3.** Let  $R$  be a commutative and unitary ring. Put

$$M = \left\{ \begin{pmatrix} x & x \\ & \end{pmatrix} \mid x \in R \right\} \subseteq M_{1 \times 2}(R) \text{ and } \Gamma = \left\{ \begin{pmatrix} n.1 \\ 0 \end{pmatrix} \mid n \in \mathbb{Z} \right\}.$$

Then,  $M$  is  $\Gamma$ -ring [5]. Define the functions  $\sigma, \tau : M \rightarrow M$  and  $D(.,.) : M \times M \rightarrow M$  as  $\sigma(X) = X$ ,  $\tau(X) = \bar{0}$  and  $D(X, Y) = X \begin{pmatrix} 1 \\ 0 \end{pmatrix} Y$ , for all  $X, Y \in M$ . It is clear that if  $X = \begin{pmatrix} x & x \\ & \end{pmatrix}$  and  $Y = \begin{pmatrix} y & y \\ & \end{pmatrix}$ , then

$$D(X, Y) = \begin{pmatrix} xy & xy \\ & \end{pmatrix}.$$

It is easily to check that  $\sigma, \tau$  are endomorphisms and  $D$  is symmetric bi- $(\sigma, \tau)$  derivation.

**Example 2.4.** Let  $R$  be a commutative and unitary ring. Put  $M = M_{1 \times 2}(R)$  and  $\Gamma = \left\{ \begin{pmatrix} n.1 \\ 0 \end{pmatrix} \mid n \in \mathbb{Z} \right\}$ . Then,  $M$  is  $\Gamma$ -ring [5]. Define the functions  $\sigma, \tau : M \rightarrow M$  and  $D(.,.) : M \times M \rightarrow M$  as  $\sigma(X) = \bar{0}$ ,  $\tau(X) = \tau \left( \begin{pmatrix} x_1 & x_2 \\ & \end{pmatrix} \right) = \begin{pmatrix} x_1 & 0 \\ & \end{pmatrix}$  and  $D(X, Y) = X \begin{pmatrix} 1 \\ 0 \end{pmatrix} Y + Y \begin{pmatrix} 1 \\ 0 \end{pmatrix} X$ , for all  $X, Y \in M$ . It is clear that if  $X = \begin{pmatrix} x_1 & x_2 \\ & \end{pmatrix}$  and  $Y = \begin{pmatrix} y_1 & y_2 \\ & \end{pmatrix}$ , then

$$D(X, Y) = \begin{pmatrix} x_1 y_1 + y_1 x_1 & x_1 y_2 + y_1 x_2 \\ & \end{pmatrix}.$$

It is easily to check that  $\sigma, \tau$  are endomorphisms and  $D$  is symmetric bi- $(\sigma, \tau)$  derivation.

**Example 2.5.** The Abelian group  $\mathbb{Z}$  with usual multiplication of numbers is a commutative  $\mathbb{Z}$ -ring. Define the functions  $\sigma, \tau : \mathbb{Z} \rightarrow \mathbb{Z}$  and  $D(.,.) : \mathbb{Z} \times \mathbb{Z} \rightarrow \mathbb{Z}$  as  $\sigma(x) = x$ ,  $\tau(x) = 0$  and  $D(x, y) = xy$ , for all  $x, y \in \mathbb{Z}$ . Then,  $\sigma, \tau$  are endomorphisms and  $D$  is symmetric bi- $(\sigma, \tau)$  derivation.

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