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Fixed Point Theorem in Fuzzy Metric Space

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ABSTRACT: In this paper we prove a fixed point theorem on a fuzzy set defining a new class of fuzzy metric space as *structure fuzzy metric space*

Key Words: Fixed point, fuzzy metric, continuous t-norm.

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1. Introduction

After Zadeh [5] introduced fuzzy sets in 1965, many researchers from various areas have developed the theory of fuzzy sets and its applications. Deng [8], Erceg [9], George and Veeramani [7] etc gave initial foundations of different forms of fuzzy metric spaces. Grebiec [3] extended Banach's [11] and Edelstein's [13] fixed point theorem in fuzzy metric space. Kramosil and Michalek [12] investigated common fixed point theorems for compatible maps. The investigation of fixed point theorems are going on fuzzy metric spaces.

In this paper we will study a fixed point theorem from view point of a new class of fuzzy metric defined on a fuzzy set. This concept came to exist when the author was investigating properties in a generalized closed set of bitopological space using topological ideal. Often topological ideal is simply stated as ideal.

A non-empty collection I of subsets of a set X is said to be an ideal if it follows following two conditions

- (1) If $A \in I$ and $B \subset A$ then $B \in I$.
- (2) If $A \in I, B \in I$, then $A \cup B \in I$.

Fixed point theorems in any areas are most useful. Mathematical economists, physicists, computer scientists etc are using fixed point theorems in their respective research areas. Now a days fuzzy fixed point theorems are also playing crucial role in mathematical economics, social choices, auction theory. One remarkable

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application of convex topological fixed point theory can be found in the 1994's Nobel laureate John Fr. Nash's classic seminal paper of equilibrium point of "Non-cooperative games" [14]. His proof is based on Kakutani's fixed point theorem [15], which is the generalization of Brouwer's fixed point theorem .

2. Preliminary definitions

In this section we discuss some existing definitions.

Definition 2.1. ([6]) A binary operation $*: [0,1] \times [0,1] \rightarrow [0,1]$ is a continuous *t*-norm if * satisfies the following conditions

- (a) * is commutative and associative;
- (b) * is continuous;
- (c) $a * 1 = a \forall a \in [0, 1];$
- (d) $a * b \leq c * d$ whenever $a \leq c$ and $b \leq d$ and $a, b, c, d \in [0, 1]$.

Definition 2.2. ([12]) Let X be a non-empty set, * be a continuous t-norm and $M: X^2 \times [0, \infty) \rightarrow [0, 1]$ be a fuzzy set. Consider the following conditions for all $x, y, z \in X$ and $t, s \in [0, \infty)$;

$$(M1) M(x, y, 0) = 0$$

- (M2) M(x, x, t) = 1
- (M3) $M(x, y, t) = 1 \Rightarrow x = y$
- (M4) M(x, y, t) = M(y, x, t)
- $(M5) M(x, y, t+s) \ge M(x, z, t) * M(z, y, s)$
- (M6) $M(x, y, .) : [0, \infty) \to [0, 1]$ is left continuous

Then (X, M, *) is said to be a fuzzy metric space.

3. Main result

This section contains some new definitions, terminologies and they are used to prove one theorem in fuzzy fixed point theory.

Definition 3.1. (X, M, *) is said to be a structure fuzzy metric space (SFMS) if it satisfies conditions (M1), (M3), (M4), (M5) and (M6) of Definition 2.2.

Example 3.2. If X = R, define a * b = ab and $M(x, y, t) = \frac{1}{2^{\frac{|x-y|+|x|+|y|}{t}}}$ then (X, M, *) is a SFMS.

Definition 3.3. A sequence $\langle x_n \rangle$ in a SFMS is said to be structure convergent if there exists $x \in X$ such that $\lim_{n\to\infty} M(x_n, x, t) = 1 \quad \forall t > 0$. Then x is said to be structure limit of $\langle x_n \rangle$ and denoted by $\lim_{n\to\infty} x_n = x$.

Definition 3.4. A sequence $\langle x_n \rangle$ in a SFMS (X, M, *) is said to be structure Cauchy sequence if for each t > 0 and $r \in N$ such that $\lim_{n\to\infty} M(x_{n+r}, x_n, t) = 1$.

(X, M, *) is said to be structure complete if every structure Cauchy sequence in it is structure convergent.

Definition 3.5. Let (X, M, *) be a SFMS, f and h are self maps on X. Then f and h are said to be normalized at x if and only if $M(fhx, hfx, t) = 1 \forall t \in [0, \infty)$.

The functions f and h are said to be normalized on X if f and h are normalized at all points x of X.

Definition 3.6. The functions f and h are said to be common domain normalized (CDN) if they are normalized at the coincidence point of f and h.

Remark 3.7. A SFMS has a unique limit point.

Proof: Proof is easy, so omitted.

Now we discuss the main theorem of this section.

Theorem 3.8. Let (X, M, *) be a SFMS and let $f, h : X \to X$ be two mappings with the following conditions,

- (a) $f(X) \subset h(X)$
- (b) Either f(X) or h(X) is structure complete
- (c) $M(fx, fy, kt) \ge M(hx, hy, t)$ for all $x, y \in X$ and $0 < k < 1, t \in [0, \infty)$
- (d) $\lim_{t\to\infty} M(x, y, t) = 1$

Then f and h have a coincidence point; moreover if f and h are CDN then f and h have a unique fixed point.

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Proof:

By condition (a), for some $x_o \in X$; we have $x_1 \in X$ such that $fx_0 = hx_1 = y_1(\text{say})$. Thus by using mathematical induction, we have $fx_n = hx_{n+1} = y_{n+1}$ where $n \in N$ and $y_0 = hx_0$.

For 0 < k < 1 and $t \in [0, \infty)$ we have $M(y_1, y_2, kt) = M(fx_o, fx_1, kt) \ge M(hx_o, hx_1, t) = M(y_0, y_1, t)$

 $M(y_2, y_3, kt) = M(fx_1, fx_2, kt) \ge M(hx_1, hx_2, t) = M(y_1, y_2, t) \ge M(y_o, y_1, \frac{t}{k}).$ Thus $M(y_2, y_3, t) \ge M(y_o, y_1, \frac{t}{k^2})$

Proceeding by mathematical induction we have $M(y_n, y_{n+1}, t) \geq M(y_o, y_1, \frac{t}{K^n})$

Thus for $r \in N, t \in [0, \infty)$ we have $M(y_n, y_{n+r}, t) \geq M(y_n, y_{n+1}, \frac{t}{2}) * M(y_{n+1}, y_{n+r}, \frac{t}{2}) \geq M(y_n, y_{n+1}, \frac{t}{2}) * M(y_{n+1}, y_{n+2}, \frac{t}{4}) * M(y_{n+2}, y_{n+r}, \frac{t}{4}) \geq \dots \geq M(y_o, y_1, \frac{t}{2k^n}) * M(y_o, y_1, \frac{t}{4k^{n+1}}) * \dots * M(y_o, y_1, \frac{t}{2^rk^{n+r-1}})$ If $n \to \infty$ then $\lim_{n\to\infty} M(y_n, y_{n+r}, t) = 1$

Thus $\langle y_n \rangle$ is a structure Cauchy sequence. Let h(X) is structure complete; then there exists $u \in h(X)$ such that $\lim_{n\to\infty} y_{n+1} = \lim_{n\to\infty} hx_{n+1} = u = \lim_{n\to\infty} fx_n$. Let hp = u for some $p \in X$

Thus $M(fp, hp, kt) = \lim_{n \to \infty} M(fp, fx_n, kt) \ge \lim_{n \to \infty} M(hp, hx_n, t) = \lim_{n \to \infty} M(u, hx_n, t) = 1$. So, fp = hp and it proves that f and h have a co-incidence point.

Now let f and h are normalized at some coincidence point θ . Thus from definition, we have $M(fh\theta, hf\theta, t) = 1 \forall t \ge 0$. This condition (M3) implies $fh\theta = hf\theta$.

Let $f\theta = h\theta = v$ then $M(fv, v, kt) = M(fv, f\theta, kt) \ge M(hv, h\theta, t) = M(hf\theta, f\theta, t) \ge M(hv, h\theta, \frac{t}{k}) \ge ... \ge M(hv, h\theta, \frac{t}{k^n})$. If $n \to \infty$ then we must have fv = v. In similar manner we can show that hv = v. Thus v is common fixed point of f and h. Proceeding in the same way we may work for h(X).

Uniqueness of fixed point: Let λ be another common fixed point of f and h; then

 $\begin{array}{ll} M(v,\lambda,kt) \,=\, M(fv,f\lambda,kt) \,\geq\, M(hv,h\lambda,t) \,=\, M(v,\lambda,t) \,=\, M(fv,f\lambda,t) \,\geq\, \\ M(hv,h\lambda,\frac{t}{k}) \,=\, M(v,\lambda,\frac{t}{k}) \,\geq\, \ldots \geq\, M(v,\lambda,\frac{t}{k^n}). \\ \end{array}$ Thus if $n \to \infty$ then $v = \lambda$. Hence the proof. \Box

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