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# Characterization Of Inextensible Flows Of Spacelike Curves With Sabban Frame In $\mathbb{S}^2_1$

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ABSTRACT: In this paper, we study inextensible flows of spacelike curves on  $\mathbb{S}_{1}^{2}$ . We obtain partial differential equations in terms of inextensible flows of spacelike curves according to Sabban frame on  $\mathbb{S}_{1}^{2}$ .

Key Words: Inextensible flows, Sabban Frame.

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#### 1. Introduction

Physically, inextensible curve and surface flows give rise to motions in which no strain energy is induced. The swinging motion of a cord of fixed length, for example, or of a piece of paper carried by the wind, can be described by inextensible curve and surface flows. Such motions arise quite naturally in a wide range of physical applications.

This study is organised as follows: Firstly, we study inextensible flows of spacelike curves on  $\mathbb{S}_1^2$ . Secondly, we obtain partial differential equations in terms of inextensible flows of spacelike curves according to Sabban frame on  $\mathbb{S}_1^2$ .

## 2. Preliminaries

The Minkowski 3-space  $\mathbb{E}^3$  provided with the standard flat metric given by

$$\langle , \rangle = -dx_1^2 + dx_2^2 + dx_3^2,$$

where  $(x_1, x_2, x_3)$  is a rectangular coordinate system of  $\mathbb{E}_1^3$ . Recall that, the norm of an arbitrary vector  $a \in \mathbb{E}_1^3$  is given by  $||a|| = \sqrt{\langle a, a \rangle}$ .  $\gamma$  is called a unit speed curve if velocity vector v of  $\gamma$  satisfies ||a|| = 1.

Denote by  $\{\mathbf{T}, \mathbf{N}, \mathbf{B}\}$  the moving Frenet–Serret frame along the spacelike curve  $\gamma$  in the space  $\mathbb{E}_1^3$ . For an arbitrary spacelike curve  $\gamma$  with first and second curvature,

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 $\kappa$  and  $\tau$  in the space  $\mathbb{E}^3_1$ , the following Frenet–Serret formulae is given

$$\begin{aligned} \mathbf{T}' &= \kappa \mathbf{N} \\ \mathbf{N}' &= -\kappa \mathbf{T} + \tau \mathbf{B} \\ \mathbf{B}' &= \tau \mathbf{N}, \end{aligned}$$
 (2.1)

where

$$\begin{aligned} \langle \mathbf{T}, \mathbf{T} \rangle &= 1, \langle \mathbf{N}, \mathbf{N} \rangle = 1, \langle \mathbf{B}, \mathbf{B} \rangle = -1, \\ \langle \mathbf{T}, \mathbf{N} \rangle &= \langle \mathbf{T}, \mathbf{B} \rangle = \langle \mathbf{N}, \mathbf{B} \rangle = 0. \end{aligned}$$

Here, curvature functions are defined by  $\kappa = \kappa(s) = \|\mathbf{T}'(s)\|$  and  $\tau(s) = -\langle \mathbf{N}, \mathbf{B}' \rangle$ .

Torsion of the spacelike curve  $\gamma$  is given by the aid of the mixed product

$$\tau = \frac{[\gamma', \gamma'', \gamma''']}{\kappa^2}.$$

Now we give a new frame different from Frenet frame. Let  $\alpha : I \longrightarrow \mathbb{S}_1^2$  be unit speed spherical curve. We denote  $\sigma$  as the arc-length parameter of  $\alpha$ . Let us denote  $\mathbf{t}(\sigma) = \alpha'(\sigma)$ , and we call  $\mathbf{t}(\sigma)$  a unit tangent vector of  $\alpha$ . We now set a vector  $\mathbf{s}(\sigma) = \alpha(\sigma) \times \mathbf{t}(\sigma)$  along  $\alpha$ . This frame is called the Sabban frame of  $\alpha$  on  $\mathbb{S}_1^2$ . Then we have the following spherical Frenet-Serret formulae of  $\alpha$ :

$$\begin{aligned}
\alpha' &= \mathbf{t}, \\
\mathbf{t}' &= -\alpha - \kappa_g \mathbf{s}, \\
\mathbf{s}' &= -\kappa_g \mathbf{t},
\end{aligned}$$
(2.2)

where  $\kappa_g$  is the geodesic curvature of the spacelike curve  $\alpha$  on the  $\mathbb{S}^2_1$  and

$$g(\mathbf{t}, \mathbf{t}) = 1, \ g(\alpha, \alpha) = 1, \ g(\mathbf{s}, \mathbf{s}) = -1,$$
  
$$g(\mathbf{t}, \alpha) = g(\mathbf{t}, \mathbf{s}) = g(\alpha, \mathbf{s}) = 0.$$

# 3. Inextensible Flows of Curves According to Sabban Frame in $\mathbb{S}_1^2$

Let  $\alpha(u,t)$  is a one parameter family of smooth spacelike curves in  $\mathbb{S}_1^2$ . The arclength of  $\alpha$  is given by

$$\sigma(u) = \int_{0}^{u} \left| \frac{\partial \alpha}{\partial u} \right| du, \qquad (3.1)$$

where

$$\left|\frac{\partial\alpha}{\partial u}\right| = \left|\left\langle\frac{\partial\alpha}{\partial u}, \frac{\partial\alpha}{\partial u}\right\rangle\right|^{\frac{1}{2}}.$$
(3.2)

The operator  $\frac{\partial}{\partial \sigma}$  is given in terms of u by

$$\frac{\partial}{\partial \sigma} = \frac{1}{\nu} \frac{\partial}{\partial u}$$

where  $v = \left| \frac{\partial \alpha}{\partial u} \right|$  and the arclength parameter is  $d\sigma = v du$ . Any flow of  $\alpha$  can be represented as

$$\frac{\partial \alpha}{\partial t} = \mathfrak{f}_1^{\mathfrak{S}} \alpha + \mathfrak{f}_2^{\mathfrak{S}} \mathbf{t} + \mathfrak{f}_3^{\mathfrak{S}} \mathbf{s}.$$
(3.3)

Letting the arclength variation be

$$\sigma(u,t) = \int_{0}^{u} v du$$

In the  $\mathbb{S}_1^2$  the requirement that the curve not be subject to any elongation or compression can be expressed by the condition

$$\frac{\partial}{\partial t}\sigma(u,t) = \int_{0}^{u} \frac{\partial v}{\partial t} du = 0, \qquad (3.4)$$

for all  $u \in [0, l]$ .

**Definition 3.1.** The flow  $\frac{\partial \alpha}{\partial t}$  in  $\mathbb{S}_1^2$  are said to be inextensible if

$$\frac{\partial}{\partial t} \left| \frac{\partial \alpha}{\partial u} \right| = 0.$$

**Lemma 3.2.** Let  $\frac{\partial \alpha}{\partial t} = \mathfrak{f}_1^{\mathbb{S}} \alpha + \mathfrak{f}_2^{\mathbb{S}} \mathbf{t} + \mathfrak{f}_3^{\mathbb{S}} \mathbf{s}$  be a smooth flow of the spacelike curve  $\alpha$ . The flow is inextensible if and only if

$$\frac{\partial v}{\partial t} - \frac{\partial \mathfrak{f}_2^8}{\partial u} = \mathfrak{f}_1^8 v - \mathfrak{f}_3^8 v k_g. \tag{3.5}$$

**Proof:** Suppose that  $\frac{\partial \alpha}{\partial t}$  be a smooth flow of the spacelike curve  $\alpha$ . From (3.3), we obtain

$$v\frac{\partial v}{\partial t} = \left\langle \frac{\partial \alpha}{\partial u}, \frac{\partial}{\partial u} \left( \mathfrak{f}_1^{\mathsf{S}} \alpha + \mathfrak{f}_2^{\mathsf{S}} \mathbf{t} + \mathfrak{f}_3^{\mathsf{S}} \mathbf{s} \right) \right\rangle.$$

By the formula of the Sabban, we have

$$\frac{\partial v}{\partial t} = \left\langle \mathbf{t}, \left( \frac{\partial \mathfrak{f}_1^{\mathsf{S}}}{\partial u} - \mathfrak{f}_2^{\mathsf{S}} v \right) \alpha + \left( \mathfrak{f}_1^{\mathsf{S}} v + \frac{\partial \mathfrak{f}_2^{\mathsf{S}}}{\partial u} - \mathfrak{f}_3^{\mathsf{S}} v \kappa_g \right) \mathbf{t} + \left( \frac{\partial \mathfrak{f}_3^{\mathsf{S}}}{\partial u} - \mathfrak{f}_2^{\mathsf{S}} v \kappa_g \right) \mathbf{s} \right\rangle.$$

Making necessary calculations from above equation, we have (3.5), which proves the lemma.

**Theorem 3.3.** Let  $\frac{\partial \alpha}{\partial t} = \mathfrak{f}_1^{\mathbb{S}} \alpha + \mathfrak{f}_2^{\mathbb{S}} \mathbf{t} + \mathfrak{f}_3^{\mathbb{S}} \mathbf{s}$  be a smooth flow of the spacelike curve  $\alpha$ . The flow is inextensible if and only if

$$\frac{\partial \mathfrak{f}_2^8}{\partial u} = \mathfrak{f}_3^8 v \kappa_g - \mathfrak{f}_1^8 v. \tag{3.7}$$

**Proof:** From (3.4), we have

$$\frac{\partial}{\partial t}\sigma(u,t) = \int_{0}^{u} \frac{\partial v}{\partial t} du = \int_{0}^{u} \left(\mathfrak{f}_{1}^{\mathfrak{S}}v + \frac{\partial\mathfrak{f}_{2}^{\mathfrak{S}}}{\partial u} - \mathfrak{f}_{3}^{\mathfrak{S}}v\kappa_{g}\right) du = 0.$$
(3.8)

Substituting (3.5) in (3.8) complete the proof of the theorem.

We now restrict ourselves to arc length parametrized curves. That is, v = 1and the local coordinate u corresponds to the curve arc length  $\sigma$ . We require the following lemma.

**Lemma 3.4.** Let  $\frac{\partial \alpha}{\partial t} = \mathfrak{f}_1^{\mathbb{S}} \alpha + \mathfrak{f}_2^{\mathbb{S}} \mathbf{t} + \mathfrak{f}_3^{\mathbb{S}} \mathbf{s}$  be a smooth flow of the spacelike curve  $\alpha$ . Then,

$$\frac{\partial \mathbf{t}}{\partial t} = \left(\frac{\partial \mathfrak{f}_1^{\mathbb{S}}}{\partial \sigma} - \mathfrak{f}_2^{\mathbb{S}}\right) \alpha + \left(\frac{\partial \mathfrak{f}_3^{\mathbb{S}}}{\partial \sigma} - \mathfrak{f}_2^{\mathbb{S}} \kappa_g\right) \mathbf{s}, \qquad (3.9)$$

$$\frac{\partial \alpha}{\partial t} = -\left(\frac{\partial \mathfrak{f}_1^{\mathfrak{d}}}{\partial \sigma} - \mathfrak{f}_2^{\mathfrak{S}}\right) \mathbf{t} + \psi \mathbf{s}, \qquad (3.10)$$

$$\frac{\partial \mathbf{s}}{\partial t} = \left(\frac{\partial \mathfrak{f}_3^{\mathbb{S}}}{\partial \sigma} - \mathfrak{f}_2^{\mathbb{S}} \kappa_g\right) \mathbf{t} - \psi \alpha, \qquad (3.11)$$

where  $\psi = \left\langle \frac{\partial \alpha}{\partial t}, \mathbf{s} \right\rangle$ .

**Proof:** Using definition of  $\alpha$ , we have

$$\frac{\partial \mathbf{t}}{\partial t} = \frac{\partial}{\partial t} \frac{\partial \alpha}{\partial \sigma} = \frac{\partial}{\partial \sigma} (\mathfrak{f}_1^{\mathrm{S}} \alpha + \mathfrak{f}_2^{\mathrm{S}} \mathbf{t} + \mathfrak{f}_3^{\mathrm{S}} \mathbf{s}).$$

Using the Sabban equations, we have

$$\frac{\partial \mathbf{t}}{\partial t} = \left(\frac{\partial \mathfrak{f}_1^{\mathbb{S}}}{\partial \sigma} - \mathfrak{f}_2^{\mathbb{S}}\right) \alpha + \left(\mathfrak{f}_1^{\mathbb{S}} + \frac{\partial \mathfrak{f}_2^{\mathbb{S}}}{\partial \sigma} - \mathfrak{f}_3^{\mathbb{S}} \kappa_g\right) \mathbf{t} + \left(\frac{\partial \mathfrak{f}_3^{\mathbb{S}}}{\partial \sigma} - \mathfrak{f}_2^{\mathbb{S}} \kappa_g\right) \mathbf{s}.$$
 (3.12)

On the other hand, substituting (3.7) in (3.12), we get

$$\frac{\partial \mathbf{t}}{\partial t} = \left(\frac{\partial \mathfrak{f}_1^{\mathbb{S}}}{\partial \sigma} - \mathfrak{f}_2^{\mathbb{S}}\right) \alpha + \left(\frac{\partial \mathfrak{f}_3^{\mathbb{S}}}{\partial \sigma} - \mathfrak{f}_2^{\mathbb{S}} \kappa_g\right) \mathbf{s}.$$

Since, we express :

$$\begin{aligned} \frac{\partial \mathfrak{f}_1^{\mathbb{S}}}{\partial \sigma} - \mathfrak{f}_2^{\mathbb{S}} + \left\langle \mathbf{t}, \frac{\partial \alpha}{\partial t} \right\rangle &= 0, \\ -\frac{\partial \mathfrak{f}_3^{\mathbb{S}}}{\partial \sigma} + \mathfrak{f}_2^{\mathbb{S}} \kappa_g + \left\langle \mathbf{t}, \frac{\partial \mathbf{s}}{\partial t} \right\rangle &= 0, \\ \psi + \left\langle \boldsymbol{\alpha}, \frac{\partial \mathbf{s}}{\partial t} \right\rangle &= 0. \end{aligned}$$

Then, a straight forward computation using above system gives

$$\frac{\partial \boldsymbol{\alpha}}{\partial t} = -\left(\frac{\partial \boldsymbol{\mathfrak{f}}_1^{\mathrm{S}}}{\partial \sigma} - \boldsymbol{\mathfrak{f}}_2^{\mathrm{S}}\right) \mathbf{t} + \psi \mathbf{s},$$
  
$$\frac{\partial \mathbf{s}}{\partial t} = \left(\frac{\partial \boldsymbol{\mathfrak{f}}_3^{\mathrm{S}}}{\partial \sigma} - \boldsymbol{\mathfrak{f}}_2^{\mathrm{S}} \kappa_g\right) \mathbf{t} - \psi \alpha,$$

where  $\psi = \left\langle \frac{\partial \boldsymbol{\alpha}}{\partial t}, \mathbf{s} \right\rangle$ . Thus, we obtain the theorem.

The following theorem states the conditions on the curvature and torsion for the flow to be inextensible.

**Theorem 3.5.** Let  $\frac{\partial \alpha}{\partial t}$  is inextensible. Then, the following system of partial differential equations holds:

$$\begin{aligned} \frac{\partial \kappa_g}{\partial \sigma} - \psi &= \quad \frac{\partial}{\partial \sigma} (\mathfrak{f}_2^{\mathbb{S}} \kappa_g) - \frac{\partial^2 \mathfrak{f}_3^{\mathbb{S}}}{\partial \sigma^2}, \\ \kappa_g \psi &= \quad \frac{\partial^2 \mathfrak{f}_1^{\mathbb{S}}}{\partial \sigma^2} - \frac{\partial \mathfrak{f}_2^{\mathbb{S}}}{\partial \sigma}. \end{aligned}$$

**Proof:** 

Using (3.9), we have

$$\begin{aligned} \frac{\partial}{\partial \sigma} \frac{\partial \mathbf{t}}{\partial t} &= \frac{\partial}{\partial \sigma} \left[ \left( \frac{\partial \mathbf{f}_1^8}{\partial \sigma} - \mathbf{f}_2^8 \right) \alpha + \left( \frac{\partial \mathbf{f}_3^8}{\partial \sigma} - \mathbf{f}_2^8 \kappa_g \right) \mathbf{s} \right] \\ &= \left( \frac{\partial^2 \mathbf{f}_1^8}{\partial \sigma^2} - \frac{\partial \mathbf{f}_2^8}{\partial \sigma} \right) \alpha + \left[ \left( \frac{\partial \mathbf{f}_1^8}{\partial \sigma} - \mathbf{f}_2^8 \right) - \kappa_g \left( \frac{\partial \mathbf{f}_3^8}{\partial \sigma} + \mathbf{f}_2^8 \kappa_g \right) \right] \mathbf{t} \\ &+ \left( \frac{\partial^2 \mathbf{f}_3^8}{\partial \sigma^2} - \frac{\partial}{\partial \sigma} (\mathbf{f}_2^8 \kappa_g) \right) \mathbf{s}. \end{aligned}$$

On the other hand, from Sabban frame we have

$$\frac{\partial}{\partial t} \frac{\partial \mathbf{t}}{\partial \sigma} = \frac{\partial}{\partial t} (-\alpha - \kappa_g \mathbf{s})$$

$$= (\psi - \frac{\partial \kappa_g}{\partial \sigma}) \mathbf{s} + \left[ \left( \frac{\partial \mathfrak{f}_1^{\mathbb{S}}}{\partial \sigma} - \mathfrak{f}_2^{\mathbb{S}} \right) + \kappa_g \left( \frac{\partial \mathfrak{f}_3^{\mathbb{S}}}{\partial \sigma} - \mathfrak{f}_2^{\mathbb{S}} \kappa_g \right) \right] \mathbf{t} + \kappa_g \psi \alpha.$$

Hence we see that

$$\frac{\partial \kappa_g}{\partial \sigma} - \psi = \frac{\partial}{\partial \sigma} (\mathfrak{f}_2^{\mathbb{S}} \kappa_g) - \frac{\partial^2 \mathfrak{f}_3^{\mathbb{S}}}{\partial \sigma^2}$$

 $\quad \text{and} \quad$ 

$$\kappa_g \psi = \frac{\partial^2 \mathfrak{f}_1^{\mathbb{S}}}{\partial \sigma^2} - \frac{\partial \mathfrak{f}_2^{\mathbb{S}}}{\partial \sigma}.$$

Thus, we obtain the theorem.

**Theorem 3.6.** Let  $\frac{\partial \alpha}{\partial t} = \mathfrak{f}_1^{\mathbb{S}} \alpha + \mathfrak{f}_2^{\mathbb{S}} \mathbf{t} + \mathfrak{f}_3^{\mathbb{S}} \mathbf{s}$  be a smooth flow of the spacelike curve  $\alpha$ . Then,

$$\kappa_g \left( \frac{\partial \mathfrak{f}_1^{\mathsf{S}}}{\partial \sigma} - \mathfrak{f}_2^{\mathsf{S}} \right) = \left( \frac{\partial \mathfrak{f}_3^{\mathsf{S}}}{\partial \sigma} + \mathfrak{f}_2^{\mathsf{S}} \kappa_g \right) + \frac{\partial \psi}{\partial \sigma}.$$

**Proof:** 

Similarly, we have

$$\frac{\partial}{\partial\sigma}\frac{\partial\mathbf{s}}{\partial t} = \frac{\partial}{\partial\sigma}\left[\left(\frac{\partial\mathfrak{f}_{3}^{\$}}{\partial\sigma} - \mathfrak{f}_{2}^{\$}\kappa_{g}\right)\mathbf{t} - \psi\alpha\right]$$
$$= \left[\left(\frac{\partial^{2}\mathfrak{f}_{3}^{\$}}{\partial\sigma} - \frac{\partial}{\partial\sigma}\left(\mathfrak{f}_{2}^{\$}\kappa_{g}\right) - \psi\right)\mathbf{t} - \kappa_{g}\left(\frac{\partial\mathfrak{f}_{3}^{\$}}{\partial\sigma} - \mathfrak{f}_{2}^{\$}\kappa_{g}\right)\mathbf{s}$$
$$+ \left[-\left(\frac{\partial\mathfrak{f}_{3}^{\$}}{\partial\sigma} + \mathfrak{f}_{2}^{\$}\kappa_{g}\right) - \frac{\partial\psi}{\partial\sigma}\right]\alpha\right].$$

On the other hand, a straightforward computation gives

$$\begin{split} & \frac{\partial}{\partial t} \frac{\partial \mathbf{s}}{\partial \sigma} = \frac{\partial}{\partial t} \left( -\kappa_g \mathbf{t} \right) \\ &= -\frac{\partial \kappa_g}{\partial t} \mathbf{t} - \kappa_g \left[ \left( \frac{\partial \mathfrak{f}_1^{\mathbb{S}}}{\partial \sigma} - \mathfrak{f}_2^{\mathbb{S}} \right) \alpha + \left( \frac{\partial \mathfrak{f}_3^{\mathbb{S}}}{\partial \sigma} - \mathfrak{f}_2^{\mathbb{S}} \kappa_g \right) \mathbf{s} \right]. \end{split}$$

Combining these we obtain the corollary.

In the light of Theorem 3.6, we express the following corollary without proof:

$$\psi = \frac{\partial^2 \mathfrak{f}_3^{\mathbb{S}}}{\partial \sigma} - \frac{\partial}{\partial \sigma} \left( \mathfrak{f}_2^{\mathbb{S}} \kappa_g \right) + \frac{\partial \kappa_g}{\partial t}.$$

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